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Method of elastic compatibility in the solution of beams of finite length on elastic foundations

Méthode de calcul élastique appliquée au calcul des poutres de longueur finie reposant sur des bases élastiques

Methode zur Berechnung von endlichen Balken auf elastischer Unterlage

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I. BEAMS AND FOUNDATION PRESSURES

1. Introduction

When a "rigid" beam carrying loads rests on elastic material, it develops pressure underneath, which is uniform throughout when centrally loaded or uniformly varying in a straight line if eccentrically loaded. If, on the other hand, the beam is "semirigid," i.e. one capable of resisting bending with certain amount of deflections, the pressure is proportional to the deflection occurring at each point. This is because the supporting soil below beams carrying engineering structures is considered to behave elastically, which tends to recover from the relative settlements when the superimposed loads on the beams are removed.

If the soil proves to be flowing plastically under loading, as may be the case with very soft clay, the beam necessitates designing as "rigid" as if floating on liquid of heavy density. On similar arguments an absolutely "flexible" member may be sufficient to bear loads lying on rather rigid supporting medium, such as rock. The appropriate stiffness required for a beam therefore depends upon the nature of the soil below. The theory also gives easy means of determining the correct value of stiffness required for a beam (Section V, examples 2 and 3).

2. Elastic line of a semi-rigid beam and the soil pressure

Fig. 1(b) shows the pressure distribution under a rigid beam LR loaded noncentrally as in (a), the straight-line variation being represented by cd from the average line LCR. If, instead, the beam is semi-rigid and rests on elastic material such that the loaded points are made to remain in one plane (not necessarily horizontal), the





(h) Final pressures under semi-rigid

Note:



Fig. 1

beam would produce deflections between the points as in (c) denoted by δ_A (termed "local deflections") and the pressure would vary as shown in (d), there being relief between the loads and increase under.

If it is now considered that according to the loading the loaded points move out of the plane so as to take different levels, the axis *LCR* of the beam would deflect to take the form *LC'R* similar to a bow of some shape either indicating "hog" or "sag" shown in (e). These deflections, represented by δ_B (termed "bow deflections"), are measured from a line connecting the ends of the beam. The deflections at various points along the beam would therefore be the algebraic sum of δ_A and δ_B , as in (f). It will be noticed that the values of δ_A are negligible as compared with δ_B .

With these deflections taking place throughout the beam, additional variation in earth pressure below comes into effect such that the lowest point in the beam exerts the highest upward pressure and the highest point has the maximum relief or reduction in upward pressure. These pressures would have at the same time the effect of reducing the deflections $\delta_A + \delta_B$ by a certain amount and adjusting themselves accordingly. The variations from the straight line *ab* of pressure distribution, which may take the two possible forms corresponding to the two deflection forms in (f), are indicated in (g).

Finally, these additional pressure variations ghk due to beam deflections, when superimposed on the average straight line ab of pressure distribution in (b), would give the two possible pressure diagrams shown in (h)—one giving maximum pressure at the ends and the other in the middle. It is therefore considered sufficient to check up pressures at the ends and at the section of maximum deflection in the middle of a beam. It should be realised, however, that the deflections referred to are only relative and are additional to the general settlement of the beam as a whole.

II. FORCES ACTING ON A BEAM AND THE PRINCIPLE OF ANALYSIS

3. Forces acting on a beam in equilibrium

The forces are considered to be divided into two systems:

(a) System 1

From the superimposed loads on a beam and its bearing area the average earth pressure w_0 per unit area is obtained. The pressure w per unit run of the beam is uniform for a beam of constant width or varying accordingly. Only the prismatic beams would be dealt with at present. Cases with non-prismatic sections will be considered in Section V, para. 13.

Consider the forces acting on a beam, as if rigid, comprising the superimposed loading above and w per unit run of earth pressure below as represented by *LRba* in fig. 1(b). If the beam is centrally loaded, this would be in equilibrium or else these forces would have an unbalanced resulting moment. This has to be balanced by an assumed straight-line variation of earth pressure from positive (acting upward) at one end to negative (acting downward) at the other, similar to that represented by line *cd* in fig. 1(b). These pressures are termed "balancing pressures" (B.P.).

The system of forces comprising these, such as would occur on a loaded beam if it were perfectly rigid, is termed F_r . The moments produced by F_r throughout the beam are M_r and the deflections measured from a line connecting the ends δ_r , which are approximately equal to $\delta_A + \delta_B$ referred to in fig. 1(f). The maximum deflection occurring in the middle of the beam in particular is termed Y_r .

(b) System 2

Due to the deflections throughout a semi-rigid beam, deviations from the straightline distribution of pressure, referred to in System 1, come to operate, having increased values at the lower points and relieved at the higher, such that the straight line representing w indicates the average of the deviations as in fig. 1(*h*), wherein *ghk* was the deviated form from line *ab*.

The increase and the relief of pressure involved in the deviations comprise the "additional variation of pressure" and such a variation, similar to that in fig. 1(g), is shown in fig. 2(a) in typical form, in which the increase is shown at the ends and relief in the middle, consequent upon the middle of the beam deflecting upwards under force system F_r . The vice-versa would be the possible alternative.

These forces in the additional pressure variation, which tend to restore the beam from the elastic deformations or deflections due to system F_r , are called "elastic restoring forces" and are comprised in a system termed F_e . The moments produced by F_e are M_e and the related deflections δ_e —in particular Y_e , the maximum in the middle.

It would be realised from fig. 1 that it is the bow deflections δ_B which are the essential factors in the development of the force system F_e and the consequent deflections δ_e , the influence of δ_A being negligible.

4. Principles of analysis

A centrally loaded beam, if rigid, would exert uniform pressure LRba shown in fig. 2(b), where La equals w, and pressure LRkhg when semi-rigid. The eccentricity



of superimposed loading would only introduce the balancing pressures in addition. Since the line $ab \inf fig. 2(a)$ represents the average of the forces F_e , the areas above and below the line should therefore be equal. To simplify calculations for moments and deflections, the variation in F_e is replaced by the straight dotted lines shown and drawn symmetrically about the centre of the beam, in lieu of line *ghk*. The maximum ordinates, both above and below the line *ab*, in the variation are represented by *fw*

per unit run or fw_0 per unit area, f being a factor or coefficient. The maximum and minimum pressures developed are therefore w_0+fw_0 and w_0-fw_0 respectively per unit area.

It would be observed that the force system F_e gives a deflection δ_e always opposite to δ_r . The total deflections throughout a beam would therefore be the sum of δ_r and δ_e algebraically, and the final maximum deflection in the middle of the beam

 $Y = \Sigma Y_r + Y_e \qquad \dots \qquad \dots \qquad \dots \qquad (4:1)$

considering the maximum deflections Y_r and Y_e to occur approximately at the same section. (It may be worth noting that the shift of the position of the maximum deflection in a prismatic beam, simply supported at the ends with a bending moment diagram of one sign, can never exceed 1/13th of the length from the centre.) The deflections are represented in fig. 3 for the beam under the system of forces in fig. 2. The original deflection is Y_r from the loading and the pressure *LRba* of system F_r , which reduces to Y due to the forces F_e having pressure ordinates fw at the centre and the ends (fig. 2(a)). For the purposes of analysis, it is necessary to ascertain the value of fw so as to obtain the pressures and the bending moments throughout a beam. To obtain the value of f, the final maximum deflection Y is to be considered first, which is dependent upon

(a) the elastic properties of the beam and

(b) the elastic properties of the soil,

so that the higher the "flexural rigidity" (EI) or the "modulus of foundation" (k_0) , the lesser is the deflection. The value of Y should be such as to be compatible with the conditions for both (a) and (b).



The value of f, related to Y, having been ascertained, the bending moment diagram for system F_e can be obtained with its maximum ordinate \overline{M}_e at the centre, where shear is nil. The moments throughout the beam would then equal $\Sigma M_r + M_e$.

For the purposes of maximum and minimum pressures underneath, the positions of fw under system F_e would be considered at the ends and in the middle of the beam where maximum deflection occurs.

III. PRESSURES AND RELATED DEFLECTIONS

5. Signs

The signs in the operations will be considered as follows:

- (i) "Moments" are positive when tension is created on the underside of beams.
- (ii) "Deflections" are positive given by positive moments.
- (iii) "f-system" is positive in the positive force system F_e causing positive moments M_e , and forces act upwards at the ends and downwards in the middle of a beam.

6. Forms of pressure variation and the related deflections Y_e

The value of deflection Y_e for a beam is connected to the force system F_e , which in turn depends on the value of f. Therefore the equations for deflections can be expressed in terms of f.

(A) Form of pressure distribution in system F_e with equal maximum ordinate above and below average

A positive force system F_e with maximum ordinates fw above and below the average line is shown in fig. 4(a), with consequent positive deflection Y_e at (b). The f-system at (a) is therefore



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positive. The arrangement could be of opposite kind with negative values. With these forces acting on a beam, the moments M_e at any section distant x from an end is given by

$$M_e = \left[\frac{x^2}{2} - \frac{2x^3}{3L}\right] fw,$$

and at centre, where x=L/2, the maximum value

$$\overline{M}_e = 0.0416 w L^2 f$$
 (6:1)

The deflection at any section distant x from an end

$$\delta_e = \frac{wf}{EI} \left[\frac{x^4}{24} - \frac{x^5}{30L} - \frac{L^3x}{96} + \frac{7L^4}{1920} \right], \text{ where } EI = \text{flexural rigidity}$$

and the maximum deflection at centre, where x=L/2

$$Y_e = 0.00365 \frac{wL^4}{EI} f$$
 (6:2)

shown at (b). The maximum and minimum pressures are w+fw and w-fw per unit run of beam respectively.

It would be observed from fig. 4 that the maximum ordinate fw of pressure reduction can never exceed w in value and thus also the maximum ordinate of pressure increase; in other words f can never exceed 1.

(B) Other forms of pressure distribution in system F_e



Fig. 5

There may be other cases of distribution such that the maximum ordinates of reduction and increase have unequal values. This would also be obvious from figs. 5(a) and (b) with positive and negative *f*-systems respectively, where some parts of the beams do not bear on the soil due to upward deflections.

For the purposes of analysis let mfw and pfw be the ordinates of the maximum reduction and increase respectively below and above the average, so that their sum

$$mfw + pfw = 2fw \qquad \dots \qquad \dots \qquad \dots \qquad \dots \qquad (6:3a)$$

as before, or

With such forms of pressure distribution as in fig. 5, mfw would be controlled by the value of w, so that mfw=w or mf=1. Then from eqn. (6:3a),

$$1+pf=2f$$
, or $pf=(2f-1)$, or

The eqn. shows that



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1. Values of "f" in the table are all absolute Notes :

2. Cases encircled are those usually covering all general practical cases 3. Intermediate values of \mathbb{N}^{e} , in $Y_{e} = NF \cdot \frac{WL^{4}}{ET}$ are given in graph. fig. 6, and of \mathbb{V}_{e}^{e} in $\overline{M}_{e} = Q \cdot wL^{2}$ in graph. fig. 12.

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Since the areas of pressures under the force system F_e above and below the average lines should be equal, it is clear from the diagrams that the ordinates pfw have to be greater than mfw, i.e. from eqn. (6:3a),

$$pfw > (2-p)fw$$
, or $p > 1$ (6:5)

This shows therefore from eqn. (6:4) that the cases would involve values of f > 1. The maximum and minimum pressures developed are 2fw and zero respectively per unit run, as would be observed from fig. 5 also.

(C) Practical considerations

To serve all practical purposes, it is assumed that:

- (i) when $f \leq 1$, the variation should be considered with equal maximum ordinates fw above and below the average, and
- (ii) when f > 1, the maximum reduction mfw has the limiting value w.

Some possible forms of pressure distribution and the connected diagrams for the force systems F_e are shown in Table I, in which the deflections Y_e are shown represented by the form

The "deflection coefficients" N against the values of f for all the cases can also be taken from fig. 6. It is to be noted that the cases 2 and

6 in Table I, having unequal ordinates mfw and pfw, would be covered by the cases 1 and 5, since mfw are not the limiting values w.

The foregoing assumptions give safe results, as the values of N for Y_e are on the higher side (see also para. 8).

When Y_r is negative, Y_e is positive with positive f-system. Cases 1 to 4 are some of the possible forms shown in Table I. Case 2 represents an ideal fourth-degree curve in view of the deflection being the fourth integral of loading and is absolutely theoretical. Under normal conditions case 1 for $f \leq 1$, and case 3 for f > 1 would be apparent.

When Y_r is positive, Y_e is negative with negative *f*-system, such that some of the possible forms may be as shown by the cases 5 to 8. Case 5 is the case 1 inverted and case 6 represents the theoretical fourth-degree curve. Under normal conditions case 5 for $f \leq 1$, and case 7 for f > 1 would be apparent, but a case with f > 1will not occur in practice when Y_r is positive (para. 7(2)(b)).



7. Factors affecting the final deflection Y in a beam

These will be considered in the following treatment of the deflections from the elastic properties of the beam and the bearing soil (para. 4):

(1) Deflections from elastic properties of beam

From eqns. (6:6) and (4:1), $Y_e = N \cdot \frac{wL^4}{EI} f$ and $Y = \Sigma Y_r + Y_e$, remembering that Y_r and Y_e are always of opposite signs.



Fig. 7

(i) When Y_r is negative, Y_e is positive with positive f-system (fig. 7(a)):

.
$$Y = -Y_r + N \cdot \frac{wL^4}{EI}(+f) = -Y_r + N \cdot \frac{wL^4}{EI}f$$
 . (B₁)

(ii) When Y_r is positive, Y_e is negative with negative f-system (fig. 7(b)):

Y:
$$Y = + Y_r - N \cdot \frac{wL^4}{EI}(-f) = + Y_r + N \cdot \frac{wL^4}{EI}f$$
 . . (B₂)

These equations stand for all values of f, whether greater, equal or less than 1.

(2) Deflections from elastic properties of soil

Since the soil reaction per unit area of foundation is assumed proportional to the settlement (para. 1), the ratio $\frac{\text{pressure per unit area }p}{\text{settlement }S}$ is a constant, termed k_0 , which is known as the "modulus of foundation." The above relation gives

Also

The modulus may vary under a beam in various ways depending upon the nature of the soil and the depths to which they occur. Let the minimum value under a beam be k_0 and the maximum nk_0 per unit area, so that n > 1. In the analysis, the variations, when taken into account, will be considered symmetrical about the centre line of the beam such that k_0 and nk_0 occur under the ends and the centre or vice versa, the variation being linear. Such variations are considered to cover the limits of all possible cases.*

In the derivation of the deflection equations, the distribution of pressure under force system F_e will be considered under two groups as follows:

(a) Force system F_e when $f \leq 1$

This system includes cases 1 and 5 of Table I, and under this group the pressure variation has equal maximum ordinates fw above and below the average (para. 6(C)).

* Advantage can also be taken of such variations in the moduli in an attempt to take account of the usual pressure variations experienced in cohesive and non-cohesive soils under engineering structures.

(i) When Y_r is negative, f-system is positive (fig. 8):



Fig. 8

In the final position of the beam the deflection (ignoring the little displacement of the position of maximum deflection from centre),

Y=settlement at centre minus settlement at ends Case 1: if k_0 is the modulus at centre and nk_0 at ends, then from eqn. (7:2):

$$Y = \frac{w_0 - fw_0}{k_0} - \frac{w_0 + fw_0}{nk_0} = -\frac{w_0}{k_0} \left[1 + \frac{1}{n} \right] f + \frac{w_0}{k_0} \left[1 - \frac{1}{n} \right] \quad . \quad . \quad (S_1)$$

Case 2: if nk_0 is the modulus at centre and k_0 at ends, then:

$$Y = \frac{w_0 - fw_0}{nk_0} - \frac{w_0 + fw_0}{k_0} = -\frac{w_0}{k_0} \left[1 + \frac{1}{n} \right] f - \frac{w_0}{k_0} \left[1 - \frac{1}{n} \right] \quad . \quad . \quad (S_2)$$

(ii) When Y_r is positive, f-system is negative (fig. 9):



Fig. 9

In the final position the maximum deflection,

Y=settlement at centre minus settlement at ends

Case 3: if k_0 is the modulus at centre and nk_0 at ends, then:

$$Y = \frac{w_0 + (-f)w_0}{k_0} - \frac{w_0 - (-f)w_0}{nk_0} = -\frac{w_0}{k_0} \left[1 + \frac{1}{n}\right] f + \frac{w_0}{k_0} \left[1 - \frac{1}{n}\right] \quad . \quad (S_3)$$

Case 4: if nk_0 is the modulus at centre and k_0 at ends, then:

$$Y = \frac{w_0 + (-f)w_0}{nk_0} - \frac{w_0 - (-f)w_0}{k_0} = -\frac{w_0}{k_0} \left[1 + \frac{1}{n}\right] f - \frac{w_0}{k_0} \left[1 - \frac{1}{n}\right] \quad . \quad . \quad (S_4)$$

Case 5: when k_0 is uniform throughout, n=1 and all the above equations become:

(b) Force system F_e when f > 1

The cases 3, 4, 7 and 8 in Table I are covered by this group, where the maximum ordinates of pressure reduction and increase are w and (2f-1)w respectively (para. 6).



It is to be realized that since some parts of the beams do not bear on the soil due to the upward deflections when f>1, the values of Y given by the soil equations would not be the true values of the maximum deflections occurring in the beams, but would only represent the values measured up to the ground lines as shown in fig. 10 by Y_s . The relationship of this Y_s with true Y may

be approximately obtained by considering the deflection curves of the beams of at least the fourth degree and are as follows when k_0 is uniform:

(i) when Y_r is negative,

for
$$f=2$$
, $Y_s=0.938 Y$
 $f=3$, $Y_s=0.803 Y$

(ii) when Y_r is positive,

or
$$f=2$$
, $Y_s=0.0625 Y$
 $f=3$, $Y_s=0.0124 Y$

Representing the number coefficients above by C, therefore, a soil equation would take the form:

 Y_s = deflection value from derived equation = CY

$$\therefore Y = \frac{1}{C}$$
 (deflection value from derived equation) . . . (7:3)

The value of C on soil with variable foundation modulus may be very different and difficult to judge. However, the value in a case can be ignored if the difference obtained between Y and Y_s is limited to, say, 10-12%, and for this purpose it is essential that for beams

(i) with negative Y_r , f must not exceed 2.5, and

f

(ii) with positive Y_r , f must not exceed 1.0.

Then the appropriate soil equations can be used without any reference to C.

It would normally be seen in practical problems that the above conditions are fulfilled, since the maximum pressures below would control the designs calling for the appropriate stiffnesses for the beams. If in a certain problem either of the above values of f is exceeded within the limiting pressure, the beam has to be made stiffer to bring in more of the unsupported portions to bear on soil (fig. 10) and thus reduce the value of f. Alternatively, for beams with positive Y_r , an effective shorter bearing length may be considered (i.e. the portion of beam actually bearing on soil in fig. 10(b)) in a revised design for both beam and soil equations.

The deflection equations when f > 1 are derived as follows, bearing in mind that mf=1 and pf=2f-1:

(i) When Y_r is negative, f-system is positive:

Case 1: k_0 at centre and nk_0 at ends:

$$Y = \frac{w_0 - mfw_0}{k_0} - \frac{w_0 + pfw_0}{nk_0} = -\frac{w_0}{k_0} \left[m + \frac{p}{n} \right] f + \frac{w_0}{k_0} \left[1 - \frac{1}{n} \right]$$
$$= -\frac{w_0}{k_0} \left[1 + \frac{2f - 1}{n} \right] + \frac{w_0}{k_0} \left[1 - \frac{1}{n} \right] = -\frac{2w_0}{nk_0} f \dots (S_1')$$

Case 2: nk_0 at centre and k_0 at ends:

$$Y = \frac{w_0 - mfw_0}{nk_0} - \frac{w_0 + pfw_0}{k_0} = -\frac{w_0}{k_0} \left[p + \frac{m}{n} \right] f - \frac{w_0}{k_0} \left[1 - \frac{1}{n} \right]$$
$$= -\frac{w_0}{k_0} \left[2f - 1 + \frac{1}{n} \right] - \frac{w_0}{k_0} \left[1 - \frac{1}{n} \right] = -\frac{2w_0}{k_0} f \dots (S_2')$$

(ii) When Y_r is positive, f-system is negative:

A case with f > 1 will not occur in practice as stated before.

Case 5: k_0 is uniform, i.e. n=1:

The above equations also give $Y = -\frac{2w_0}{k_0}f$, as eqn. (S₅).

8. Values of final deflection Y and coefficient f

As stated in para. 4, the final deflection Y should satisfy conditions for both beam and soil properties. Therefore for a particular case, a beam equation and an appropriate soil equation for deflections have to be solved simultaneously to obtain the values of Y and f with proper signs.

In connection with the deflection Y_e in a particular beam equation, it is evident that when $f \leq 1$, $Y_e = 0.0037 \frac{wL^4}{EI} f$. This value of N = 0.0037 may therefore be used in all practical cases as a trial value for solving the equations. If from the solution the absolute value obtained for f is ≤ 1 , the result would be satisfactory; and if >1, a revision in the coefficient would be necessary, which can then be judged easily from fig. 6, bearing in mind the probable nature of distribution of F_e .

It may be worth while to note that a higher value of N than anticipated for a beam, if adopted, should normally give safer results, as the solution would yield lesser values of f and Y. In doubtful cases, however, a problem may be solved with two beam equations representing possible upper and lower limits in the values of Y_e , and the worse values of obtained moment and shear taken care of at each section. Similarly in a case of doubtful variation in the foundation modulus along a beam, the solution may also be carried out with two soil equations representing the upper and the lower limits.

IV. FINAL MOMENTS AND PRESSURES

9. Moments M_e

These are obtained from force system F_e when the value of f is determined from the solution of the deflection equations. Referring to the Table I it would be clear that even when the value of f is known, the moments M_e , with central ordinate \overline{M}_e , would depend upon the nature of distribution of force system F_e in a particular case.

The M_e -curve was considered in fig. 4 with value of $f \leq 1$ and was of the third degree. With the increase in the value of f, the shape of the curve tends to change only slightly. For the convenience of obtaining values at intermediate points along the length of a beam, it is sufficient to consider an M_e -diagram as triangular with the







ordinate \overline{M}_e at centre. Such a diagram is shown in fig. 11 replacing the third-degree curve when $f \leq 1$. The differences in the ordinates are only little.

The values of \overline{M}_e under various cases are given in Table I in the form $\overline{M}_e = Q \cdot wL^2$, where Q is a function of f. The values of Q under different cases can also be taken from fig. 12 against the values of f. As stated in para. 6(C), cases 1, 3 and 5 of Table I would normally cover all practical cases.

10. Final moments M

(ii)

At any section of a beam, the final moment $M = \Sigma M_r + M_e$ (para. 4), M_r and M_e being opposite in signs. Note that M_e would carry the sign of f.

11. Final pressures under a beam and settlements

From the value of f obtained, the pressures would be as follows (para. 6):

(i) when $f \leq 1$, $p_{max} = w_0 + f w_0$ per unit area

These would be clear from the pressure distributions shown in Table I. The balancing

pressures B.P. due to the eccentricity of loading on a beam from force system F_r are also to be taken into account.

The settlements at various points in a beam can then be obtained from the related pressures, employing eqn. (7:2).

V. EXAMPLES

12(a). Beam on soil with constant foundation modulus

Example 1*. A weightless beam 10 inches by 8 inches with the loading shown in fig. 13(a) is resting on an elastic foundation having a modulus of 200 lb./in.³ The elastic modulus of the beam material is $1.5 \cdot 10^6$ lb./in.² Obtain the moments and pressures throughout the beam.

Thus, L=120 in., I=426.7 in.⁴, E=1.5. 10⁶ lb./in.² and $k_0=200$ lb./in.³ Total load=P+48q=5,000+4,800=9,800 lb.

Bearing area of foundation= $120 \cdot 10 = 1,200 \text{ in.}^2$

:
$$w_0 = \frac{9,800}{1,200} = 8.16$$
 lb./in.², and $w = 8.16$. 10=81.6 lb./in. run.

Unbalanced moment and balancing pressures B.P.:

Considering w acting below and taking moments about point 6, unbalanced moment= $5,000 \cdot 90+4,800 \cdot 44-9,800 \cdot 60=73,200$ in.-lb.

Section modulus of foundation area

$$Z = \frac{10 \cdot 120^2}{6} = 24,000 \text{ in.}^3$$
73 200

:. End pressures in B.P. = $\pm \frac{73,200}{24,000} = \pm 3.05 \text{ lb./in.}^2$

 $=\pm 30.5$ lb./in. run

Moments M_r :

With the superimposed load above and w and B.P. below, values of moments obtained are shown in Fig. 13(b).

Deflection Y_r :

From the M_r diagram, the value of maximum deflection Y_r is found conveniently by the "Conjugate Beam Method" at a section 54 in. from the left end as 0.0810 in., which is positive in value. (Approximation of the M_r diagram by straight lines, shown dotted, is permissible for this purpose.)

Beam equation:

Since Y_r is positive, eqn. (B₂) of para. 7 applies,

Soil equation:

Since k_0 is constant and Y_r is positive, eqn. (S₅) of para. 7 applies,

:
$$Y = -\frac{2w_0}{k_0}f = -\frac{2 \cdot 8 \cdot 16}{200}f = -0.0816f$$
 (2)

Solution:

Solving eqns. (1) and (2) above, f = -0.45 and Y = +0.0368 in. The value of f

* The example is taken from *Beams on Elastic Foundation*, by M. Hetenyi, University of Michigan **Press**, Ann Arbor, 1946, p. 47.



Fig. 13

obtained is <1, which shows that the value of N adopted in beam equation is suitable (para. 8). Note that the value is in the negative system.

Moment \overline{M}_e :

Since f < 1 and Y, is +ve, case 5 of Table I applies. From fig. 12, Q=0.0187 against f=0.45.

 \therefore $\overline{M}_e = -QwL^2 = -0.0187 \cdot 81.6 \cdot 120^2 = -22,000$ in.-lb. This is the central ordinate of the triangular M_e diagram.

Final moments M (in.-lb.):

Section	Mr	Me	M	Hetenyi's values of M
2 3 Centre 4 5	+48,040 +29,700 +30,000 +27,870 +10,880	11,000 19,100 22,000 16,150 7,340	+37,040 +10,600 + 8,000 +11,720 + 3,540	+35,460 (calculated) + 9,623

These are shown in fig. 13(c), with the M_r and M_e diagrams superimposed. Final pressures p (lb./in.²): $fw_0=0.45 \cdot 8.16=3.67$

Section	w ₀	fw ₀	B.P.	р	Hetenyi's values of p
1 Section of	+8.16	-3.67	+3.05	+ 7.54	+ 6.07
max. defin. 6	+8·16 +8·16	+3.67 -3.67	+0.31 - 3.05	+12·14 + 1·44	+10.39 (centre) + 1.26

These are shown in fig. 13(d).

Settlements (inches): From eqn. (7:2), $S=p/k_0$

Section	S .	Hetenyi's values of S		
l	$7 \cdot 54/200 = 0 \cdot 038$	0.03036		
Near centre	$12 \cdot 14/200 = 0 \cdot 061$	0.05193		
6	$1 \cdot 44/200 = 0 \cdot 0072$	0.00628		

Settlements at intermediate points may be found by obtaining the relative deflections. Fig. 14. shows the beam in its final position.



12(b). Value of I for beam to control deflection

Example 2. What should be the value of I for the beam in example 1 if the maximum deflection Y is not to exceed 0.02 in.?

Using the soil eqn., Y = -0.0816f, $\therefore +0.02 = -0.0816f$, $\therefore f = -0.245$

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Withdrawing the value of I, the beam eqn. is expressed as $Y = +\frac{34 \cdot 6}{I} + \frac{41 \cdot 8}{I} f$, and substituting the appropriate values.

$$+0.02 = \frac{1}{I} [34.6 + 41.8(-0.245)] = \frac{1}{I} (34.6 - 10.2) = \frac{24.4}{I}$$

$$\therefore I = \frac{24.4}{0.02} = 1,210 \text{ in.}^4$$

With 10 in. width, depth $d = \sqrt{\frac{121}{h}} = \sqrt{\frac{121}{10}} = 11.32$ in.

12(c). Value of I for beam to control pressure

Example 3. What may be the value of *I* for the beam of example 1 if the maximum pressure underneath is not to exceed 14 lb./in.²?

We have seen that in the middle of the beam

 $p_{max} = w_0 + fw_0 + B.P. = +8.16 + 8.16f + 0.31 = +8.47 + 8.16f$

14 = +8.47 + 8.16f, $\therefore f = \frac{5.53}{8.16} = 0.675$ (in negative system).

From the soil equation, therefore,

Y = -0.0816f = -0.0816(-0.675) = +0.055 in. Withdrawing the value of I from the beam eqn.,

$$Y = \frac{1}{I} [34.6 + 41.8f]$$

and substituting the appropriate values

$$+0.055 = \frac{1}{I}[34.6 + 41.8(-0.675)] = \frac{6.4}{I}$$

$$\therefore I = \frac{6.4}{0.055} = 116 \text{ in.}^4$$

With 10 in. width, depth $d = \sqrt[3]{\frac{12.116}{10}} = 5.18 \text{ in.}$

12(d). Beam on soil with variable foundation modulus

Example 4. Solve the problem in example 1 assuming that the modulus varies from 200 lb./in.³ at centre to 350 lb./in.³ at ends. Then, the beam equation, as before

$$Y = +0.0810 + 0.0980f \quad . \quad . \quad . \quad . \quad . \quad . \quad (1)$$

Soil eqn.:

$$n = \frac{350}{200} = 1.5$$

Y, is +ve, and in anticipation of $f \leq 1$, eqn. (S₃) applies.

$$\therefore \quad Y = -\frac{8 \cdot 16}{200} \left[1 + \frac{1}{1 \cdot 5} \right] f + \frac{8 \cdot 16}{200} \left[1 - \frac{1}{1 \cdot 5} \right] = -0.0683f + 0.0135 \quad . \quad . \quad . \quad . \quad (2)$$

Solving (1) and (2), f = -0.405 and Y = +0.0413 in. From fig. 12, case 5, Q = 0.0168. $\therefore \quad \overline{M}_e = -0.0168 \cdot 81.6 \cdot 120^2 = -19,700 \text{ in.-lb.}$

The diagram is represented by M_{e1} in fig. 13.

$$M_{max}$$
 at section 2=+48,040 $-\frac{19,700}{2}$ =+38,190 in.-lb.
 p_{max} at middle =+8.16+(0.405.8.16)+0.31=11.77 lb./in.²

13. Beam with non-prismatic section having constant width

The procedure is the same as shown before except for a little adjustment involved in the value of Y_e . For this purpose an equivalent "constant moment of inertia" is obtained for the same amount of maximum deflection within the beam. The example, which follows, will clarify the problem.

Example 5*. A continuous footing 30 ft. wide, having a cross-section as shown in fig. 15, rests on soil with a modulus of 300 kips/ft.^3 There is a line load of 150 kips/ft. run at the centre and the elastic modulus of the material may be taken as 432,000 kips/ft.² The weight of the beam is neglected.

Thus,

$$k_0 = \frac{300,000}{12^3} = 173 \text{ lb./in.}^3 \text{ (uniform)},$$

$$E = \frac{432,000,000}{12^2} = 3,000,000 \text{ lb./in.}^2,$$

$$P = 150 \text{ kips/ft.} = 150,000 \text{ lb./ft.}$$

Considering 1 ft. length of footing as width of beam, bearing area = 360 in. $\times 12$ in. Also

$$w = \frac{150,000}{360} = 416$$
 lb./in. run, and $w_0 = \frac{416}{12} = 34.8$ lb./in.²

The system F_r is shown in (a). The loading being symmetrical about the centre there is no B.P.

 M_r :

With the load P above and w acting below, the moments developed in the beam are shown in (c). The variations in the moment of inertia are shown in (b). Y_r :

To obtain the maximum deflection Y_r , a diagram for M_r/I is obtained first as in (d). From this the maximum deflection at centre, $Y_r = +0.196$ in. Y_e :

Equivalent constant moment of inertia I_c for the beam to give the same amount of maximum deflection in the middle under force system F_e is to be considered first. For this purpose the beam is to be considered loaded at the centre with a concentrated unit load when supported at the ends. This is reasonable, since the M_e diagram is nearly triangular, which is corresponding to the above condition of loading.

Let the moment diagram from the unit load be called M_1 and the maximum deflection Y_1 . Then the central ordinate of M_1 diagram

$$\overline{M}_1 = + \frac{W \cdot L}{4} = + \frac{1 \cdot 360}{4} = +90$$
 in.-lb. . . . (13:1)

shown in (e). The maximum deflection with I_c ,

$$Y_1 = +\frac{1}{48} \cdot \frac{WL^3}{EI_c} = +\frac{1}{48} \cdot \frac{1 \cdot 360^3}{3,000,000 \cdot I_c} = +\frac{0.324}{I_c} \text{ in.-lb.} \quad . \quad (13:2)$$

With the present variable I, the maximum deflection Y_1 is found from M_1/I diagram as in (f), and the value at centre

From eqns. (13:2) and (13:3),

* The example is taken from "Successive Approximation for Beams on Elastic Foundations," by E. P. Popov, *Proc.A.S.C.E.*, May, 1950, vol. 76, Separate No. 18, p. 5.





The procedure hereafter is as for a prismatic beam with constant moment of inertia I_c . Beam equation:

Since Y_r is +ve, eqn. (B₂) applies.

$$\therefore \quad Y = +0.196 + 0.0037 \cdot \frac{416 \cdot 360^4}{3,000,000 \cdot 89,000} f = +0.196 + 0.097f \cdot ... \quad (1)$$

Soil equation:

 k_0 being uniform eqn. (S₅) applies.

$$\therefore \quad Y = -\frac{2 \cdot 34 \cdot 8}{173} f = -0.402f \qquad . \qquad . \qquad . \qquad (2)$$

Solution:

From eqns. (1) and (2) above, f = -0.392 and Y = +0.158 in.

 \overline{M}_e :

Since case 5 of Table I applies, from fig. 12, Q=0.0163.

 $\therefore \quad \overline{M}_e = -0.0163 \cdot 416 \cdot 360^2 = -880,000 \text{ in.-lb.}$

M (in.-lb.):

These are shown in (g).

p (lb./in.²):

 $fw_0 = 0.392 \cdot 34.80 = 13.65$

Section	wo	fw ₀	р	Popov's values of p
1	+34·80	-13.65	+21·15	+18·85
4	+34·80	+13.65	+48·45	+45·00

These are shown in (h).

VI. REMARKS

14. Remarks

Comparing the present method with that developed mathematically from differential equations for elastic lines, the solution is reliable for a beam having a value of

 $\lambda l \gg 2\pi$, when Y_r is negative, and

 $\lambda l \gg \pi$, when Y, is positive,

where $\lambda = \sqrt[4]{\frac{bk_0}{4EI}}$ and b = width of beam.

With higher value of λl the pressures are in error, as the deflection curve of the beam develops reverse curvatures at distant points from the loads. The maximum possible bending moment will not, however, exceed the value obtained by this method, and in practical designs with reinforced concrete foundation beams, recourse may have to be made to nominal reinforcements in the compression faces.

Summary

The forces acting on a beam are considered to be divided into two systems:

System 1, comprising the superimposed loads on the beam and the pressure underneath such as would occur if the beam were perfectly rigid, due consideration being given to the eccentricity of loading, if any, involving straight-line variation of pressure, and System 2, comprising only the additional variation of pressure under the beam due to deflections throughout from the average straight-line variation obtained in System 1.

The additional pressure variation of System 2 related to the deflections is obtained from consideration of

(a) the elastic properties of the beam, and

(b) the elastic properties of the soil.

This being known, the corresponding moment diagram is readily approximated. This diagram, when superimposed on that due to System 1, gives the final moment values throughout the beam.

The advantage of the method lies in obtaining readily

(1) the final bending moment diagram,

(2) the maximum deflection occurring in a beam, and

(3) the maximum and minimum pressures underneath.

Other advantages available from the theory include the determination of the appropriate moment of inertia of a beam to control

(a) maximum deflection, and

(b) maximum pressure underneath.

The method can be applied to beams, prismatic or non-prismatic, with any kind of loading and solutions give with comparative ease results which are reasonably close to those obtained by accurate analysis. The paper includes illustrative examples already solved by other methods.

Résumé

On considère que les forces agissant sur une poutre se divisent en deux systèmes:

ler Système: comprenant les charges appliquées à la poutre et la pression s'exerçant en-dessous, telles qu'elles se présenteraient si la poutre était parfaitement rigide, compte tenu éventuellement de l'excentricité de la charge, impliquant variation de pression en ligne droite.

2ème Système: comprenant uniquement la variation additionnelle de pression sous la poutre, due aux déviations d'un bout à l'autre, à partir de la variation moyenne en ligne droite obtenue dans le ler système.

La variation additionnelle de pression du deuxième système, relative au déviations, est obtenue par la prise en considération:

(a) des propriétés élastiques de la poutre,

(b) des propriétés élastiques du sol.

Celles-ci étant connues, on obtient sans difficulté une approximation de la courbe du moment correspondant. Cette courbe, lorsqu'on la superpose à celle qui résulte du premier système, donne les valeurs définitives du moment d'un bout à l'autre de la poutre.

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L'avantage de la méthode réside dans le fait qu'on obtient instantanément:

(1) la courbe définitive du moment de flexion,

(2) la déviation maximum se produisant dans une poutre,

(3) les pressions maximum et minimum en-dessous.

Parmi les autres avantages offerts par cette théorie, il fait mentionner la détermination du moment d'inertie d'une poutre permettant d'équilibrer:

- (a) la déviation maximum,
- (b) la pression maximum au-dessous.

La méthode peut être appliquée aux poutres prismatiques ou autres, avec n'importe quelle sorte de charge et les solutions donnent, avec une facilité relative, des résultats qui sont suffisamment proches de ceux que l'on obtient par une analyse rigoureuse. L'exposé contient des exemples explicatifs déjà résolus par d'autres méthodes.

Zusammenfassung

Die auf einen Balken wirkenden Kräfte werden in zwei Systeme eingeteilt:

System 1 umfasst die auf ihn wirkenden Nutzlasten sowie die auf der Unterlage entstehenden Pressungen für den Fall, dass der Balken vollkommen steif ist. Eine etwaige Exzentrizität der Belastung wird dabei im Sinne eines geradlinigen Verlaufs der Pressungen berücksichtigt.

System 2 umfasst lediglich die zusätzlichen Aenderungen dieser Pressungen entsprechend den Durchbiegungen, die von der für das System 1 gewählten mittleren geradlinigen Verteilung abweichen.

Die zusätzliche Aenderung der Pressungen im System 2 ergibt sich aus der Betrachtung

(a) der elastischen Eigenschaften des Balkens,

(b) der elastischen Eigenschaften des Untergrundes.

Diese Eigenschaften als bekannt vorausgesetzt, lässt sich die entsprechende Momentenlinie schnell und in guter Annäherung ermitteln. Sie ergibt, nach Ueberlagerung derjenigen des Systems 1 den endgültigen Momentenverlauf im Balken.

Der Vorteil der Methode besteht darin, dass

- (1) der endgültige Momentenverlauf im Balken,
- (2) die grösste Durchbiegung des Balkens,
- (3) die grösste und kleinste Pressung der Unterlage schnell und leicht ermittelt werden kann.

Als weiterer Vorteil ergibt sich aus der Theorie die Möglichkeit, das Trägheitsmoment eines Balkens zweckmässig so festzulegen, dass

(a) die grösste Durchbiegung,

(b) die grösste Pressung im Untergrund innerhalb bestimmter Grenzen bleiben.

Das Verfahren kann auf Balken prismatischen oder nicht prismatischen Querschnitts und für jede Art von Belastungen angewandt werden. Es liefert auf verhältnismässig einfache Weise Ergebnisse, welche mit den genauen Lösungen gut übereinstimmen. Der Aufsatz enthält Beispiele, die zum Vergleich auch mit Hilfe anderer Methoden gelöst wurden.

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