On an improved theory for Dr. Basler's theory

- Autor(en): **Fujii, Tokio**
- Objekttyp: Article
- Zeitschrift: IABSE congress report = Rapport du congrès AIPC = IVBH Kongressbericht

Band (Jahr): 8 (1968)

PDF erstellt am: **12.07.2024**

Persistenter Link: https://doi.org/10.5169/seals-8785

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On an Improved Thory for Dr. Basler's Theory

Essai d'amélioration de la théorie de Basler

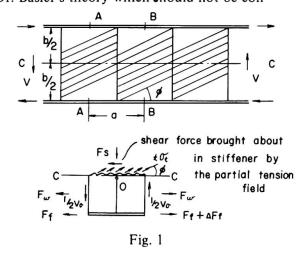
Verbesserungsversuch der Basler-Theorie

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1. Introduction

It is thought to be reasonable to design plate girders based on the ultimate strength because of the large capacity of post-buckling strength. In view of this fact, Dr. Basler's ingenious theories are considered to be very worthy. It is the author's opinion, however, that there are some problems to be discussed in his theories, especially on the shear strength. The first problem is that the contribution of flange rigidity to the tension field action is neglected in Dr. Basler's theory which **s**hould not be con-

sidered negligible in many cases. As the results of this assumption the direction of the tension field derived by Dr. Basler always gives less slope than the diagonal of web panel. But, when flanges are sufficiently strong and web buckling stress is small, direction of tension field should approach to 45° to the flange as shown by Wagner⁽¹⁾. The next problem is that Dr. Basler derived an equation of equilibrium of forces from Fig. 1, but he neglected the shear force brought about in the stiffener at section 0, which must be accounted for if a partial tension field is assumed. Moreover, the



effect of compressive force brought about in flanges by the tension field action on the interaction curves under combined bending and shear is neglected in Dr. Basler's theory. This is unsafety side because the compressive force overlaps the compressive force caused by bending.

The author tried to introduce a new approach of finding the shear strength of girders in post-buckling range with the above-mentioned points taken into consideration.

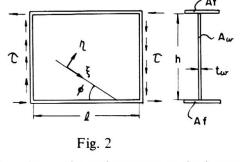
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2. Theory $^{(2)}$

In the following discussion, it is assumed that plate girders are so designed as not to give rise to lateral or local buckling of flanges, and that the stiffeners are designed sufficiently strong, too.

If a pure shearing stress field is assumed within a girder panel which is surrounded by upper and lower flanges and vertical stiffeners (Fig. 2), stresses in the web in the direction making an angle ϕ with the flange are given by the following equations,

$$\begin{aligned}
\sigma_{\xi} &= \mathcal{T} \quad \sin 2\phi, \quad \mathcal{T}_{\xi\gamma} &= \mathcal{T} \quad \cos 2\phi, \\
\sigma_{\gamma} &= -\mathcal{T} \quad \sin 2\phi.
\end{aligned}$$
(1)

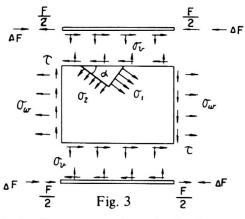


Therefore, if the web buckling stress is denoted by \mathcal{T}_{cr} , the web stresses at the instant of buckling can be expressed as,

$$\begin{aligned}
\sigma_{\xi cr} &= \mathcal{T}_{cr} \sin 2\phi, \\
\sigma_{\eta cr} &= -\mathcal{T}_{cr} \sin 2\phi, \\
\mathcal{T}_{\xi \gamma cr} &= \mathcal{T}_{cr} \cos 2\phi.
\end{aligned}$$
(2)

In order to compute stresses after the web has buckled, the author assumes that the direction of the principal tensile stress σ_1 concides with that of waves of buckling and that the principal compressive stress σ_2 in the direction perpendicular to σ_1 is kept of the same stress value as that at the instant of the web buckling in the same direction. Once the action of the tension field comes out, stress σ_v and σ_w come into existence in the periphery of the panel to equilibrate

Let \propto be an angle between the principal stress σ_1 and the flanges, then the formulae of equal librium of former on the bound



formulas of equi-librium of forces on the boundary with the flanges are written in the forms,

$$\mathbf{U}_1 \quad \sin \mathbf{x}_+ \quad \mathbf{U}_2 \cos \mathbf{x}_- = \mathbf{T}_{\mathbf{v}} \quad , \tag{3}$$

$$(\sigma_1 - \sigma_2) \sin \alpha \cos \alpha = \tau$$
, (4)

Shearing force is,

$$V = \mathcal{R} t_{\omega} \mathcal{T} = A_{\omega} (\sigma_1 - \sigma_2) \sin \alpha \cos \alpha , \qquad (5)$$

where

 f_{ω} is depth of web, f_{ω} is thickness of web,

and $A_w = h t_w$ is sectional area of web.

 σ_2 is given from the afore-mentioned assumption in the form,

$$\sigma_2 = - \mathcal{C}_{cr} \sin 2 \alpha \tag{6}$$

Suppose the web be yielded uniformly all over the panel under theses stress conditions. By using Tresca's yield condition.

By substituting Eqs (6) and (7) into Eq. (3)

$$\frac{\sigma_{v}}{\sigma_{w_{Y}}} = \sin^{2} \alpha - \frac{v_{er}}{2} \sin 2 \alpha, \qquad (8)$$

where,

$$\mathcal{V}_{cr} = \frac{\mathcal{T}_{cr}}{\mathcal{T}_{wY}}$$

By substituting Eqs. (6), (7) and (8) into Eq. (5) and by making it dimensionless, the following equation is obtained.

$$v = \frac{\left(1 - 2\frac{\sigma_{\overline{v}}}{\sigma_{\overline{w}\gamma}}\right)v_{cr} + \sqrt{1 + v_{cr}^2 - \left(1 - 2\frac{\sigma_{\overline{v}}}{\sigma_{\overline{w}\gamma}}\right)^2}}{1 + v_{cr}^2}$$
(9)

where,

and

where,

$$\mathcal{V} = \frac{\nabla}{\nabla_{\mathbf{p}}}$$

$$\nabla_{\mathbf{p}} = A_{\mathbf{w}} \mathcal{T}_{\mathbf{w} \mathbf{Y}} \qquad \text{is plastic shear force,}$$

 $\mathcal{T}_{wY} = \frac{\mathcal{T}_{wY}}{z}$ is yield shear stress of web.

The value of σ_{v} varies with the bending deformation of the flanges, but it reaches its maximum when the flanges start to collapse forming the plastic hinges at the both ends supported by vertical stiffeners and at the midspan of flanges (Fig. 4).

By applying the theory of simple plasticity to the flanges which are regarded as beams of rectangular cross section subjected to uniformly distributed load with both ends fixed, this maximum value is obtained by the following formula,

$$\frac{1}{4} l^{2} t_{w} \sigma_{v max} = A_{f} t_{f} \sigma_{fY} \qquad (10)$$

$$A_{f} = b_{f} t_{f} \text{ is sectional area of tlange,}$$

$$b_{f} \text{ is width of flange,}$$

$$t_{f} \text{ is thickness of tlange,} \qquad Fig. 4$$

and σ_{fY} is yield stress of flanges.

Strictly speaking web portions adjacent to the flanges should be considered to act as a part of the flanges and the influences of axial force and shearing force in flanges on collapse should be taken into account.

However, it is considered that these influences are not significant, because the former and the latter influences cancel each other. Therefore, Eq. (10) will be exact for practical application.

The value of $(\sigma_v / \sigma_{w_Y})$ which makes Eq. (9) maximum will be obtained by putting $\partial v / (\sigma_v / \sigma_{w_Y}) = 0$ as follows. $\sigma_v / \sigma_{w_Y} = (1 - v_{cr})/2$ (11)

11. Bg. Schlussbericht

The maximum value of v or ultimate shear force V_u is derived from Eqs. (9), (10) and (11) in the following way.

If
$$(1 - \mathcal{V}_{cr}) < \mathcal{E}$$
, by substituting Eq. (11) into Eqs. (8) and (9),
 $\mathcal{V}_{u} = 1$, (12)
If $\mathcal{E} \leq (1 - \mathcal{V}_{cr})$, by substituting Eq. (10) into Eqs. (8) and (9),
 $\mathcal{V}_{u} = \frac{(1 - \mathcal{E}) \mathcal{V}_{cr} + \sqrt{1 + \mathcal{V}_{cr}^{2} - (1 - \mathcal{E})^{2}}}{1 + \mathcal{V}_{cr}^{2}}$ (13)
 $\tan \alpha = \frac{\mathcal{V}_{cr} + \sqrt{1 + \mathcal{V}_{cr}^{4} - (1 - \mathcal{E})^{2}}}{2 - \mathcal{E}}$
If $\mathcal{E} = 0$ or the rigidity of the flanges can be neglected,
 $\mathcal{V}_{uo} = 2 \mathcal{V}_{cr} / (1 + \mathcal{V}_{cr}^{2})$

(13')

 $\tan \alpha_{o} = \mathcal{V}_{cr}$

On the other hand, if the stiffener space is comparatively small, the portion where tension field action is directly anchored by the axial force of the stiffeners is formed in the web as indicated by hatched portion in Fig. 5.

This portion can bear higher tension than the neighboring triangular portions because the condition given in Eq. (3) need not be satisfied in this portion.

Therefore, this portion can be assumed to be under the yielded condition and the principal tensile stress σ_1 in this portion is given as

(14)

Eqs. (3), (4) and (6) are applicable to stresses in neighboring triangular portions. From the equilibrium of forces, 15' E F

$$V = A_{w} (1 - \lambda \tan \alpha) \tau' + \lambda A_{w} \tan \alpha \cdot \tau$$

$$= A_{w} \{(1 - \lambda \tan \alpha) (\sigma_{1}' - \sigma_{2}) + \lambda \tan \alpha$$

$$(\sigma_{1} - \sigma_{2}) \} \sin \alpha \cdot \cos \alpha$$

$$(15)$$
en the girder collapses with a partial tension
$$dF' = \frac{1}{2} \qquad \frac{1}{\tau} \qquad \frac$$

 $\frac{1}{1} + \frac{1}{1} + \frac{1}$

Whe field formed nearly in the direction of the diagonal of the panel as mentioned above, the prerequisite is

$$\sigma_{\tilde{i}} \leq \sigma_{\tilde{i}}'$$
 (16)

and the flange must satisfy Eq. (10)

From Eqs. (6), (3) and (10)

$$\frac{\sigma_1}{\sigma_{w\gamma}} = \frac{\frac{\varepsilon}{2} + \frac{v_{er}}{2} \sin 2\alpha \cos^2 \alpha}{\sin^2 \alpha}$$
(17)
By substituting Eqs. (6) (14) and (17) into Eq. (15) and making it dimensionless

By substituting Eqs. (6), (14) and (17) into Eq. (15) and making it dimensionless,

$$V = E\lambda + \lambda V_{cr} \sin 2\alpha + (1 - \lambda \tan \alpha) \sin 2\alpha$$
 (18)

Eq. (18) takes its maximum value for a certain value of α which is obtained by putting

 $\partial U_{\partial \alpha} = 0$, as follows,

$$\tan 2 \alpha = (1 + \lambda \mathcal{V}_{cr}) / \lambda \tag{19}$$

By substituting this value into Eq. (18) the ultimate shear force in this case will be

$$\mathcal{U}_{\mu} = \sqrt{\lambda^2 + (1 + \lambda \mathcal{U}_{cr})^2} - (1 - \varepsilon)\lambda$$
(20)

Particularly, if $\varepsilon = 0$,

$$\mathcal{U}_{\mu o} = \sqrt{\lambda^2 + (1 + \lambda \mathcal{V}_{cr})^2} - \lambda \tag{20'}$$

The prerequisite condition under which the ultimate shear load is given by Eq. (20) is obtained by substituting Eqs. (14), (17) and (19) into Eq. (16) in the form

$$\varepsilon \leq 1 - \frac{\lambda + \mathcal{V}_{cr} (1 + \lambda \mathcal{V}_{cr})}{\sqrt{\lambda^2 + (1 + \lambda \mathcal{V}_{cr})^2}}, \qquad (21)$$

or

$$\lambda \leq \frac{1}{\sqrt{\varepsilon} + \overline{v_{cr}^{2}}} \frac{\sqrt{1 - \varepsilon} - \overline{v_{cr}}}{1 + \overline{v_{cr}^{2}}} \equiv \lambda_{cr}$$
(21')

Ultimate shear forces are summarized from the above-mentioned results as shown in Table -1. Values of \mathcal{V}_{cr} are calculated by the following equations which are modified Johnson's column formula.

$$\begin{aligned}
\mathcal{U}_{cr} &= \frac{1}{12(1-\nu^2)} \left(\frac{1}{\mathcal{T}_{wY}}\right) \left(\frac{1}{\mathcal{T}_{w}}\right), \quad \mathcal{U}_{cr} \leq 0.5 \\
\mathcal{U}_{cr} &= 1 - \frac{3(1-\nu^2)}{k_s \pi^2} \left(\frac{1}{\mathcal{T}_{wY}}\right) \left(\frac{1}{\mathcal{T}_{w}}\right)^2, \quad \mathcal{U}_{cr} > 0.5
\end{aligned}$$
(22)

Where γ is Poisson's ratio and k_s is a buckling coefficient depend on λ and constraint conditions around a panel.

Since the stiffeners are usually almost equal in thickness to the web while flanges are much thicker than the web, it seems appropriate to consider that the web is fixed at the flanges and supported at the stiffeners.

And the theoretical values using the buckling coefficient calculated for a panel fixed at the flanges shows a good coincidence with the experimental values.

		Table 1				
Failure mode	Condition	Ultimate shear force	Notations			
	(1- Ucr) < E		$F_{2} = A_{f} = t_{f}$ $V \downarrow \qquad \downarrow $			
	$ -\frac{\lambda+\mathcal{V}_{tr}(1+\lambda\mathcal{V}_{tr})}{\sqrt{\lambda^{2}+(1+\lambda\mathcal{V}_{tr})^{2}}}$ $< \varepsilon \leq (1-\mathcal{V}_{cr})$	$ \mathcal{U}_{\mu} = \frac{(1-\epsilon) \mathcal{U}_{\epsilon \mu} + \sqrt{1 + \mathcal{U}_{\epsilon}^{2} - (1-\epsilon)^{2}}}{1 + \mathcal{U}_{\epsilon}^{2}} \\ \text{tand} = \frac{\mathcal{U}_{\epsilon \mu} + \sqrt{1 + \mathcal{U}_{\epsilon}^{2} - (1-\epsilon)^{2}}}{2-\epsilon} $	λ=¼h : aspect ratio d : inclination of tension field σ _{wy} : yield stress of web σ _{ty} : " flange			
	$\xi \leq \frac{\lambda + \mathcal{U}_{F}(1 + \lambda \mathcal{U}_{F})}{\sqrt{\chi} + (1 + \lambda \mathcal{U}_{F})^{2}}$	$\mathcal{V}_{\mu} = \sqrt{\lambda^{2} + (1 + \lambda \mathcal{V}_{eF})^{2}} - (1 - \varepsilon)\lambda$ $\tan 2\alpha = \frac{1 + \lambda \mathcal{V}_{eF}}{\lambda}$	$T_{cr}: web buckling stress E = \frac{8}{N} \frac{tf}{h} \frac{At \sigma_{fY}}{Ar \sigma_{uY}} V_{cr} = T_{cr} / T_{uY} V_u = Vu / Aw T_{uY}$			

3. Comparison with the test results

The results of the test conducted on girders G-6, G-7, G-8, G-9, by Dr. Basler et al.,⁽³⁾ girders H-1, H-2 by Cooper et al.,⁽⁴⁾ a girder B by Dr. Konishi et al., ⁽⁵⁾ are compared with the author's and Dr. Basler's theories. The experimental and the theoretical values are summarized in Table -2.

For the author's theory, the values calculated for the web with simply-supported periphery are also shown in round brackets for comparison with the values calculated for the web fixed along the flanges. The values of which were obtained by neglecting the effect of flange stiffeness on tension field are also shown.

The flanges of girders H 1, H 2, G $1^{(8)}$ and G $2^{(8)}$ were provided with doublers of cover plates as shown in Fig. 6. In these cases, values of which gives the effect of rigidity of flanges were calculated by the following formula, presuming that the flanges and the cover plates act as independent simple beams.

$$\mathcal{E} = \frac{8}{\lambda^2} \frac{\left(t_f^2 b_f \mathcal{T}_{fY} + t_c^2 b_c \mathcal{T}_{CY}\right)}{h A_{\omega} \mathcal{T}_{\omega_Y}}$$
(23)

where

 t_c is thickness of cover plate,

b. is width of cover plate,

and \mathcal{O}_{cy} is yield stress of cover plate.

As was indicated in Section 1, Dr. Basler's theoretical formula was derived from equilibrium condition of forces, the shear force acting in the stiffeners being neglected. If this shear force be taken into account, the ultimate shear force is given by the following equation in stead of Eq. (12) of ref. (8),

$$\overline{V_{\mu}} = \overline{V_{p}} \left[\frac{\overline{\mathcal{L}_{cr}}}{\overline{\mathcal{L}_{Y}}} + \frac{\sqrt{3}}{2} \left(1 - \frac{\overline{\mathcal{L}_{cr}}}{\overline{\mathcal{L}_{Y}}} \right) \sqrt{1 + \lambda^{2}} - \lambda \right]$$
(24)

Theoretical values corrected by Eq. (24) are by $10 \sim 40\%$ lower than the original values.

In Table-2, Dr. Basler's theoretical values in column (9) are the original values, and the values corrected by Eq. (24) are excluded. In column (10) are given ratios of the experimental values to the original and the corrected theoretical values, the latter ratios being given in square brackets for com-

parison with the former ratios. It is observed that the differences between the original theoretical values of \mathcal{T}_{u} and the experimental ones exceed 10% in ten girders, nearly half of the specimens, and that the corrected theoretical values become considerably smaller than experimental values.

The author's theoretical values, which include the contribution of flange stiffeness on tension field and on the boundary condition of the web, as the author wishes to propose, the author's theoretical values coincide well with the experimental values. Fig. 6



For the 25 girders examined, differences between the theoretical and the experimental values were within 10%, only one exception being 22% for the girder G 6.

Table-2 Comparison of the theoretical values with the experimental values.

		Experimental values						. Theoretical values							
Ref.		Wet	b Flange						Basler		Author				
No.	Girder	h×t.	r.,	by x ty be x te	Gir Gir	х	<u>h</u> t	ℤ*	V.ª		ν,	V _{er}	Une	V.	Vut V
	(1)	(2)	(3)	(4)	(5)	(6)	(7)	(8)	(9)	(10)	(11)	(12)	(13)	(14)	(15)
		in in	k.s.i.	in in	k.s.i.			kips	kips		kips				
(3)	G6-T1 G6-T2 G6-T3 G7-T1 G7-T2 G8-T1	50 x 0.193 50 x 0.196 50 x 0.197	36.7 38.2	12.13 x 0.778 12.19 x 0.768 12.00 x 0.750	.37.9 	1.5 0.75 0.5 1.0 	259 255 254	116 150 177 140 145 85	112 157 180 142 142 76	1.04 (1.58) 0.95 (1.28) 0.98 (1.15) 0.98 (1.41) 1.02 (1.46) 1.12 (1.70)	177 180 188	0.237 (0.155) 0.355 (0.293) 0.592 (0.551) 0.275 (0.210) 0.275 (0.210) 0.211 (0.121)	0.552 (0.441) 0.722 (0.685) 0.889 (0.871) 0.620 (0.570) 0.620 (0.570) 0.416 (0.295)	0.606 (0.525) 0.877 (0.849) 1.00 (1.00) 0.740 (0.690) 0.740 (0.690) 0.456 (0.334)	1.08 0.97 1.00 1.05 1.09 0.99
	G9-T1 G9-T2	50 x 0.131	44.5	12.00 x 0.750	41.8	 1.5	382	48 75	51 85	0.94 [1.63] 0.89 [1.49]	146	0.080 (0.048) 0.093 (0.058)	0.246 (0.211) 0.383 (0.335)	0.298 (0.263) 0.486 (0.438)	1.10 1.06
(4)	HI-TI	50 x 0.393	108.1	18.06 x 0.980	106.4	3.0	127	630	473	1.33 [1.89]	1060	0.299 (0.190)	0.550 (0.383)	0.620 (0.473)	0.96
	H1-T2	-	-	18.06 x 0.980 17.03 x 0.982	106.4 105.8	1.5		769	710	1.08 [1.56]	-	0.338 (0.221)	0.626 (0.506)	0.790 (0.684)	0.92
	H2-T1	50 x 0.390	110.2	18.06 x 1.006 17.09 x 1.008	105.5 108.8	1.0	128	917	875	1.05 [1.45]	1075	0.369 (0.283)	0.695 (0.627)	0.929 (0.711)	0.92
	H2-T2	-	-			0.5		1125	1143	0.98 [1.09]	"	0.689 (0.687)	0.935 (0.934)	1.00 (1.00)	1.05
		mm mm	kg/mm	2 mm mm	kg/mm ²			ton	ton		ton				
(5)	В	1200 x 4.5	50.0	240 x 12	50.0	1.0	267	76	91.4	0.83 [1.18]	135	0.130 (0.100)	0.510 (0.485)	0.553 (0.528)	1.02
(6)	G1-1	1200 x 6.6	49.6	250 x 23	51.0	3.0	182	99	81.5	1.21 [1.83]	196	0.222 (0.141)	0.433 (0.319)	0.471 (0.357)	1.07
	G1-2			250 x 23 250 x 13	51.0 46.0	1.5	-	129	126	1.03 [1.57]	"	0.251 (0.164)	0.535 (0.450)	0.633 (0.548)	1.04
	G2-1	950 x 6.6		250 x 19	53.0	3.0	144	98	73.3	1.34 [1.83]	155.5	0.355 (0.226)	0.630 (0.439)	0.658 (0.480)	0.96
	G2-2	-	-	250 x 19 250 x 13	53.0 46.0	1.5		125	107	1.17 [1.63]		0.402 (0.262)	0.695 (0.547)	0.802 (0.668)	1.00
(7)	G1 G2	440 x 8	44.0	160 x 30 200 x 30	42.0	2.61	55	82 84	96.7	0.85 0.87	77.5	0.910 (0.860)	0.996 (0.989)	1.00 (0.999) 1.00 (1.00)	1.06 1.08
	G3 G4 G5	560 x 8		160 x 30 250 x 30		2.63 3.57 2.68	70 	99 97 107	102.2 99.1 102.2	0.97 [1.01] 0.98 [1.01] 1.05 [1.09]	98.5 "	0.854 (0.773) 0.849 (0.759) 0.854 (0.772)	0.988 (0.963) 0.987 (0.963) 0.988 (0. 96 8)	0.997 (0.985) 0.995 (0.980) 0.999 (0.990)	1.01 0.99 1.09
	G6 G7					1.25		120	102.2	1.06 1.07 [1.09]		0.875 (0.818) 0.854 (0.772)	0.992 (0.980) 0.988 (0.968)	1.00 (1.00) 0.999 (0.990)	1.09
	G8 G9	720 x 8		160 x 30 250 x 30	, r, ,	2.78	90 "	93 failured by lateral buckling of flange 118 98.5 1.20 [1.32] 127 0.758 (0.622)					0.962 (0.897)	0.979 (0.931)	0.95

(): calculated values supposing simply supported along the flanges []: $\overline{V_{\mu}}^{m}$ calculated by Eq. (24)

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SUMMARY

While extremely ingenious, and accepted generally to be well applicable to the design of plate girders, Dr. Basler's theories would appear to the present author to possess certain weak points, particularly with respect to the determination of shear strength. The present author has attempted a new approach to the question of finding the ultimate shear strength of plate girders. The improvement thus introduced has resulted in better agreement between theoretical values and those obtained empirically in experiments conducted at the Lehigh University and in Japan.

RÉSUMÉ

Bien qu'extrêmement ingénieuses et acceptées généralement comme bien valable pour les calculs de poutres à âme pleine, les théories du Dr. Basler, selon l'avis du présent auteur, comportent quelques points faibles surtout concernant la résistance au cisaillement. L'auteur a essayé d'aborder d'une direction nouvelle la question de trouver la résistance extrême au cisaillement des poutres à âme pleine. L'amélioration ainsi introduite a apportée une meilleur concordance entre les valeurs théoriques et celles empiriques mesurées aux essais effectuées à l'Université de Lehigh et au Japon.

ZUSAMMENFASSUNG

Obwohl ausgezeichnet und allgemein anerkannt für die Anwendung zur Erstellung von Vollwandträgern, erscheint es dem Verfasser doch angebracht, auf einige schwache Punkte, besonders im Hinblick auf die Bestimmung der Scherfestigkeit, hinzuweisen. Die vorgeschlagene Verbesserung ergab eine bessere Uebereinstimmung zwischen den theoretischen Werten und jenen, die durch Versuche sowohl an der Lehigh Universität als auch in Japan erzielt wurden.

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