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$SL_n(\mathbb{Z}[t])$ is not FP_{n-1}

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Abstract. We prove the result from the title using the geometry of Euclidean buildings.

Mathematics Subject Classification (2000). 20F65.

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1. Introduction

Little is known about the finiteness properties of $SL_n(\mathbb{Z}[t])$ for arbitrary *n*.

In 1959 Nagao proved that if k is a field then $SL_2(k[t])$ is a free product with amalgamation [Na]. It follows from his description that $SL_2(\mathbb{Z}[t])$ and its abelianization are not finitely generated.

In 1977 Suslin proved that when $n \ge 3$, $SL_n(\mathbb{Z}[t])$ is finitely generated by elementary matrices [Su]. It follows that $H_1(SL_n(\mathbb{Z}[t]), \mathbb{Z})$ is trivial when $n \ge 3$.

More recent, Krstić and McCool proved in [Kr-Mc] that $SL_3(\mathbb{Z}[t])$ is not finitely presented.

In this paper we provide a generalization of the results of Nagao and Krstić–McCool mentioned above for the groups $SL_n(\mathbb{Z}[t])$.

Theorem 1. If $n \ge 2$, then $SL_n(\mathbb{Z}[t])$ is not of type FP_{n-1} .

Recall that a group Γ is *of type* FP_m if there exists a projective resolution of \mathbb{Z} as the trivial $\mathbb{Z}\Gamma$ module

$$P_m \to P_{m-1} \to \cdots \to P_1 \to P_0 \to \mathbb{Z} \to 0$$

where each P_i is a finitely generated, projective $\mathbb{Z}\Gamma$ module.

In particular, Theorem 1 implies that there is no $K(SL_n(\mathbb{Z}[t]), 1)$ with finite (n-1)-skeleton, where K(G, 1) is the Eilenberg–Mac Lane space for G.

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1.1. Outline of the paper. The general outline of this paper is modelled on the proofs in [Bu-Wo1] and [Bu-Wo2], though some important modifications have to be made to carry out the proof in this setting.

As in [Bu-Wo1] and [Bu-Wo2], our approach is to apply Brown's filtration criterion [Br1]. Here we will examine the action of $SL_n(\mathbb{Z}[t])$ on the locally infinite Euclidean building for $SL_n(\mathbb{Q}((t^{-1})))$. In Section 2 we will show that the infinite groups that arise as cell stabilizers for this action are of type FP_m for all m, which is a technical condition that is needed for our application of Brown's criterion.

In Section 3 we will demonstrate the existence of a family of diagonal matrices that will imply the existence of a "nice" isometrically embedded codimension 1 Euclidean space in the building for $SL_n(\mathbb{Q}((t^{-1})))$. In [Bu-Wo1] analogous families of diagonal matrices were constructed using some standard results from the theory of algebraic groups over locally compact fields. Because $\mathbb{Q}((t^{-1}))$ is not locally compact, our treatment in Section 3 is quite a bit more hands on.

Section 4 contains the main body of our proof. We use translates of portions of the codimension 1 Euclidean subspace found in Section 3 to construct spheres in the Euclidean building for $SL_n(\mathbb{Q}((t^{-1})))$ (also of codimension 1). These spheres will lie "near" an orbit of $SL_n(\mathbb{Z}[t])$, but will be nonzero in the homology of cells "not as near" the same $SL_n(\mathbb{Z}[t])$ orbit. Theorem 1 will then follow from Brown's criterion.

1.2. Background material. Our proof relies heavily on the geometry of the Euclidean and spherical buildings for $SL_n(\mathbb{Q}((t^{-1})))$. A good source of information for the former topic is Chapter 6 of [Br2]. For the latter, we recommend Chapter 5 of [Ti].

2. Stabilizers

Lemma 2. If X is the Euclidean building for $SL_n(\mathbb{Q}((t^{-1})))$, then the $SL_n(\mathbb{Z}[t])$ stabilizers of cells in X are FP_m for all m.

Proof. Let $x_0 \in X$ be the vertex stabilized by $SL_n(\mathbb{Q}[[t^{-1}]])$. We denote a diagonal matrix in $GL_n(\mathbb{Q}((t^{-1})))$ with entries $s_1, s_2, \ldots, s_n \in \mathbb{Q}((t^{-1}))^{\times}$ by $D(s_1, s_2, \ldots, s_n)$, and we let $\mathfrak{S} \subseteq X$ be the sector based at x_0 and containing vertices of the form $D(t^{m_1}, t^{m_2}, \ldots, t^{m_n})x_0$ where each $m_i \in \mathbb{Z}$ and $m_1 \ge m_2 \ge \cdots \ge m_n$.

The sector \mathfrak{S} is a fundamental domain for the action of $SL_n(\mathbb{Q}[t])$ on X (see [So]). In particular, for any vertex $z \in X$, there is some $h'_z \in SL_n(\mathbb{Q}[t])$ and some integers $m_1 \ge m_2 \ge \cdots \ge m_n$ with $z = h'_z D_z(t^{m_1}, t^{m_2}, \ldots, t^{m_n}) x_0$. We let $h_z = h'_z D_z(t^{m_1}, t^{m_2}, \ldots, t^{m_n})$.

For any $N \in \mathbb{N}$, let W_N be the (N + 1)-dimensional vector space

$$W_N = \{ p(t) \in \mathbb{C}[t] \mid \deg(p(t)) \le N \}$$

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$$\operatorname{SL}_n(\mathbb{Z}[t])$$
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which is endowed with the obvious \mathbb{Q} -structure. If N_1, \ldots, N_{n^2} in \mathbb{N} are arbitrary then let

$$G_{\{N_1,\dots,N_{n^2}\}} = \left\{ x \in \prod_{i=1}^{n^2} W_{N_i} \mid \det(x) = 1 \right\}$$

where det(x) is a polynomial in the coordinates of x. To be more precise this is obtained from the usual determinant function when one considers the usual $n \times n$ matrix presentation of x, and calculates the determinant in Mat_n($\mathbb{C}[t]$).

For our choice of vertex $z \in X$ above, the stabilizer of z in $SL_n(\mathbb{Q}((t^{-1})))$ equals $h_z SL_n(\mathbb{Q}[[t^{-1}]])h_z^{-1}$. And with our fixed choice of h_z , there clearly exist some $N_i^z \in \mathbb{N}$ such that the stabilizer of the vertex z in $SL_n(\mathbb{Q}[t])$ is $G_{\{N_1^z,...,N_{n^2}^z\}}(\mathbb{Q})$. Furthermore, conditions on N_i^z force a group structure on $G_z = G_{\{N_1^z,...,N_{n^2}^z\}}$. Therefore, the stabilizer of z in $SL_n(\mathbb{Q}[t])$ is the \mathbb{Q} -points of the affine \mathbb{Q} -group G_z , and the stabilizer of z in $SL_n(\mathbb{Z}[t])$ is $G_z(\mathbb{Z})$.

The action of $SL_n(\mathbb{Q}[t])$ on X is type preserving, so if $\sigma \subset \mathfrak{S}$ is a simplex with vertices z_1, z_2, \ldots, z_m , then the stabilizer of σ in $SL_n(\mathbb{Z}[t])$ is simply

$$(G_{z_1}\cap\cdots\cap G_{z_m})(\mathbb{Z}).$$

That is, the stabilizer of σ in $SL_n(\mathbb{Z}[t])$ is an arithmetic group, and Borel–Serre proved that any such group is FP_m for all m [Bo-Se].

3. Polynomial points of tori

This section is devoted exclusively to a proof of the following

Proposition 3. There is a group $A \leq SL_n(\mathbb{Z}[t])$ such that the following holds:

- (i) $A \cong \mathbb{Z}^{n-1}$.
- (ii) There is some $g \in SL_n(\mathbb{Q}((t^{-1})))$ such that gAg^{-1} is a group of diagonal matrices.
- (iii) No nontrivial element of A fixes a point in the Euclidean building for $SL_n(\mathbb{Q}((t^{-1})))$.

The proof of this proposition is modelled on a classical approach to finding diagonalizable subgroups of $SL_n(\mathbb{Z})$. The proof will take a few steps.

3.1. A polynomial over $\mathbb{Z}[t]$ with roots in $\mathbb{Q}((t^{-1}))$. Let $\{p_1, p_2, p_3, ...\} = \{2, 3, 5, ...\}$ be the sequence of prime numbers. Let $q_1 = 1$. For $2 \le i \le n$, let $q_i = p_{i-1} + 1$.

Let $f(x) \in \mathbb{Z}[t][x]$ be the polynomial given by

$$f(x) = \left[\prod_{i=1}^{n} (x+q_i t)\right] - 1.$$

It will be clear by the conclusion of our proof that f(x) is irreducible over $\mathbb{Q}(t)$, but we will not need to use this directly.

Lemma 4. There is some $\alpha \in \mathbb{Q}((t^{-1}))$ such that $f(\alpha) = 0$.

Proof. We want to show that there are $c_i \in \mathbb{Q}$ such that if $\alpha = \sum_{i=0}^{\infty} c_i t^{1-in}$ then $f(\alpha) = 0$.

To begin let $c_0 = -1$. We will define the remaining c_i recursively. Define $c_{i,k}$ by $\alpha + q_k t = \sum_{i=0}^{\infty} c_{i,k} t^{1-in}$. Thus, $c_{i,k} = c_i$ when $i \ge 1$, each $c_{0,k}$ is contained in \mathbb{Q} , and $c_{0,1} = 0$.

That α is a root of f is equivalent to

$$1 = \prod_{k=1}^{n} (\alpha + q_k t) = \prod_{k=1}^{n} \left(\sum_{i=0}^{\infty} c_{i,k} t^{1-in} \right) = \sum_{i=0}^{\infty} \left(\sum_{\sum_{k=1}^{n} i_k = i}^{n} \left(\prod_{k=1}^{n} c_{i_k,k} \right) \right) t^{n(1-i)}.$$

Our task is to find c_m 's so that the above is satisfied.

Note that for the above equation to hold we must have

$$0 \cdot t^{n} = \sum_{\sum_{k=1}^{n} i_{k}=0} \left(\prod_{k=1}^{n} c_{i_{k},k} \right) t^{n(1-0)}.$$

That is,

$$0=\prod_{k=1}^n c_{0,k}$$

which is an equation we know is satisfied because $c_{0,1} = 0$. Now assume that we have determined $c_0, c_1, \ldots, c_{m-1} \in \mathbb{Q}$. We will find $c_m \in \mathbb{Q}$.

Notice that the first coefficient in our Laurent series expansion above which involves c_m is the coefficient for the t^{-nm} term. This follows from the fact that each i_k is nonnegative.

Since

$$\sum_{\sum_{k=1}^{n} i_k = m} \left(\prod_{k=1}^{n} c_{i_k,k} \right)$$

is the coefficient of the t^{-nm} term in the expansion of 1, we have

$$0 = \sum_{\sum_{k=1}^{n} i_k = m} \left(\prod_{k=1}^{n} c_{i_k,k} \right).$$

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The above equation is linear over \mathbb{Q} in the single variable c_m and the coefficient of c_m is nonzero. Indeed, $\sum_{k=1}^{n} i_k = m$, each $i_k \ge 0$, and $c_0, \ldots, c_{m-1} \in \mathbb{Q}$ are assumed to be known quantities. Thus, $c_m \in \mathbb{Q}$.

3.2. Matrices representing ring multiplication. By Lemma 4 we have that the field $\mathbb{Q}(t)(\alpha) \leq \mathbb{Q}((t^{-1}))$ is an extension of $\mathbb{Q}(t)$ of degree *d* where $d \leq n$. It follows that $\mathbb{Z}[t][\alpha]$ is a free $\mathbb{Z}[t]$ -module of rank *d* with basis $\{1, \alpha, \alpha^2, \ldots, \alpha^{d-1}\}$.

For any $y \in \mathbb{Z}[t][\alpha]$, the action of y on $\mathbb{Q}(t)(\alpha)$ by multiplication is a linear transformation that stabilizes $\mathbb{Z}[t][\alpha]$. Thus, we have a representation of $\mathbb{Z}[t][\alpha]$ into the ring of $d \times d$ matrices with entries in $\mathbb{Z}[t]$. We embed the ring of $d \times d$ matrices with entries in $\mathbb{Z}[t]$ into the upper left corner of the ring of $n \times n$ matrices with entries in $\mathbb{Z}[t]$.

By Lemma 4

$$\prod_{i=1}^{n} (\alpha + q_i t) = 1$$

so each of the following matrices are invertible:

$$\alpha + q_1 t, \ \alpha + q_2 t, \ \ldots, \ \alpha + q_n t.$$

(We will be blurring the distinction between the elements of $\mathbb{Z}[t][\alpha]$ and the matrices that represent them.)

For $1 \le i \le n-1$, we let $a_i = \alpha + q_{i+1}t$. Since a_i is invertible, it is an element of $GL_n(\mathbb{Z}[t])$, and hence has determinant ± 1 . By replacing each a_i with its square, we may assume that $a_i \in SL_n(\mathbb{Z}[t])$ for all *i*. We let $A = \langle a_1, \ldots, a_{n-1} \rangle$ so that *A* is clearly abelian as it is a representation of multiplication in an integral domain. This group *A* will satisfy Proposition 3.

3.3. *A* is free abelian on the a_i . To prove part (i) of Proposition 3 we have to show that if there are $m_i \in \mathbb{Z}$ with

$$\prod_{i=1}^{n-1} a_i^{m_i} = 1$$

then each $m_i = 0$. But the first nonzero term in the Laurent series expansion for α is -t, which implies that the first nonzero term in the Laurent series expansion for each a_i is $-t + q_{i+1}t = p_it$. Hence, the first nonzero term of

$$\prod_{i=1}^{n-1} a_i^{m_i} = 1$$

is

$$\prod_{i=1}^{n-1} (p_i t)^{m_i} = t^0.$$

Thus

$$\prod_{i=1}^{n-1} p_i^{m_i} = 1$$

and it follows by the uniqueness of prime factorization that $m_i = 0$ for all *i* as desired.

Thus, part (i) of Proposition 3 is proved.

3.4. *A* is diagonalizable. Recall that α is a $d \times d$ matrix with entries in $\mathbb{Z}[t]$ where *d* is the degree of the minimal polynomial of α over $\mathbb{Q}(t)$. Let that minimal polynomial be q(x). Because the characteristic of $\mathbb{Q}(t)$ equals 0, q(x) has distinct roots in $\mathbb{Q}(t)(\alpha)$.

Let Q(x) be the characteristic polynomial of the matrix α . The polynomial Q also has degree d and leading coefficient ± 1 with $Q(\alpha) = 0$. Therefore, $q = \pm Q$. Hence, Q has distinct roots in $\mathbb{Q}(t)(\alpha)$ which implies that α is diagonalizable over $\mathbb{Q}(t)(\alpha) \leq \mathbb{Q}((t^{-1}))$. That is to say that there is some $g \in SL_n(\mathbb{Q}((t^{-1})))$ such that $g\alpha g^{-1}$ is diagonal.

Because every element of $\mathbb{Z}[t][\alpha]$ is a linear combination of powers of α , we have that $g(\mathbb{Z}[t][\alpha])g^{-1}$ is a set of diagonal matrices. In particular, we have proved part (ii) of Proposition 3.

3.5. *A* has trivial stabilizers. To prove part (iii) of Proposition $\frac{3}{3}$ we begin with the following

Lemma 5. If $\Gamma \leq SL_n(\mathbb{Q}[t])$ is bounded under the valuation for $\mathbb{Q}((t^{-1}))$, then the eigenvalues for any $\gamma \in \Gamma$ lie in $\overline{\mathbb{Q}}$.

Proof. We let X be the Euclidean building for $SL_n(\mathbb{Q}((t^{-1})))$. By the Bruhat–Tits fixed point theorem, $\Gamma z = z$ for some $z \in X$.

Let $x_0 \in X$ be the vertex stabilized by $SL_n(\mathbb{Q}[[t^{-1}]])$. We denote a diagonal matrix in $GL_n(\mathbb{Q}((t^{-1})))$ with entries $s_1, s_2, \ldots, s_n \in \mathbb{Q}((t^{-1}))^{\times}$ by $D(s_1, s_2, \ldots, s_n)$, and we let $\mathfrak{S} \subseteq X$ be the sector based at x_0 and containing vertices of the form $D(t^{m_1}, t^{m_2}, \ldots, t^{m_n})x_0$ where each $m_i \in \mathbb{Z}$ and $m_1 \ge m_2 \ge \cdots \ge m_n$.

The sector \mathfrak{S} is a fundamental domain for the action of $SL_n(\mathbb{Q}[t])$ on X [So] which implies that there is some $h \in SL_n(\mathbb{Q}[t])$ with $hz \in \mathfrak{S}$.

Clearly we have $(h\Gamma h^{-1})hz = hz$, and since eigenvalues of $h\Gamma h^{-1}$ are the same as those for Γ , we may assume that Γ fixes a vertex $z \in \mathfrak{S}$.

Fix $m_1, \ldots, m_n \in \mathbb{Z}$, $m_1 \ge \cdots \ge m_n \ge 0$, such that $z = D(t^{m_1}, \ldots, t^{m_n})x_0$. Without loss of generality, there is a partition of $n - \text{say} \{k_1, \ldots, k_\ell\}$ – such that

$$\{m_1,\ldots,m_n\} = \{q_1,\ldots,q_1, q_2,\ldots,q_2, \ldots, q_\ell,\ldots,q_\ell\}$$

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where each q_i occurs exactly k_i times and

$$q_1 > q_2 > \cdots > q_\ell.$$

We have that $D(t^{m_1}, \ldots, t^{m_n})^{-1} \Gamma D(t^{m_1}, \ldots, t^{m_n}) x_0 = x_0$. That gives us, $D(t^{m_1}, \ldots, t^{m_n})^{-1} \Gamma D(t^{m_1}, \ldots, t^{m_n}) \subset SL_n(\mathbb{Q}[[t^{-1}]])$. Furthermore, a trivial calculation of resulting valuation restrictions for the entries of

$$D(t^{m_1},...,t^{m_n})$$
SL_n($\mathbb{Q}[[t^{-1}]]$) $D(t^{m_1},...,t^{m_n})^{-1}$

shows that Γ is contained in a subgroup of $SL_n(\mathbb{Q}((t^{-1})))$ that is isomorphic to

$$\prod_{i=1}^{\ell} \operatorname{SL}_{k_i}(\mathbb{Q}) \ltimes U$$

where $U \leq SL_n(\mathbb{Q}((t^{-1})))$ is a group of upper-triangular unipotent matrices.

The lemma is proved.

Our proof of Proposition 3 will conclude by proving

Lemma 6. No nontrivial element of A fixes a point in the Euclidean building for $SL_n(\mathbb{Q}((t^{-1})))$.

Proof. Suppose $a \in A$ fixes a point in the building. We will show that a = 1. Let $F(x) \in \mathbb{Z}[t][x]$ be the characteristic polynomial for $a \in SL_n(\mathbb{Z}[t])$. Then

$$F(x) = \pm \prod_{i=1}^{n} (x - \beta_i)$$

where each $\beta_i \in \mathbb{Q}((t^{-1}))$ is an eigenvalue of *a*. By the previous lemma, each $\beta_i \in \overline{\mathbb{Q}}$. Hence, each $\beta_i \in \mathbb{Q} = \overline{\mathbb{Q}} \cap \mathbb{Q}((t^{-1}))$. It follows that $F(x) \in \mathbb{Z}[x]$ so that each β_i is an algebraic integer contained in \mathbb{Q} . We conclude that each β_i is contained in \mathbb{Z} .

Recall, that *a* has determinant 1, and that the determinant of *a* can be expressed as $\prod_{i=1}^{n} \beta_i$. Hence, each β_i is a unit in \mathbb{Z} , so each eigenvalue $\beta_i = \pm 1$. It follows – by the diagonalizability of *a* – that *a* is a finite order element of $A \cong \mathbb{Z}^{n-1}$. That is, a = 1.

We have completed our proof of Proposition 3.

4. Body of the proof

Let $P \leq SL_n(\mathbb{Q}((t^{-1})))$ be the subgroup where each of the first n-1 entries along the bottom row equal 0. Let $R_u(P) \leq P$ be the subgroup of elements that contain a $(n-1) \times (n-1)$ copy of the identity matrix in the upper left corner. Thus $R_u(P) \cong \mathbb{Q}((t^{-1}))^{n-1}$ with the operation of vector addition.

Let $L \leq P$ be the copy of $SL_{n-1}(\mathbb{Q}((t^{-1})))$ in the upper left corner of $SL_n(\mathbb{Q}((t^{-1})))$. We apply Proposition 3 to L (notice that the n in the proposition is now an n-1) to derive a subgroup $A \leq L$ that is isomorphic to \mathbb{Z}^{n-2} . By the same proposition, there is a matrix $g \in L$ such that gAg^{-1} is diagonal.

Let $b \in SL_n(\mathbb{Q}((t^{-1})))$ be the diagonal matrix given in the notation from the proofs of Lemmas 2 and 5 as $D(t, t, \dots, t, t^{-(n-1)})$. Note that $b \in P$ commutes with L, and therefore, with A. Thus the Zariski closure of the group generated by b and A determines an apartment in X, namely $g^{-1}A$ where A is the apartment corresponding to the diagonal subgroup of $SL_n(\mathbb{Q}((t^{-1})))$.

4.1. Actions on $g^{-1}A$. If $x_* \in g^{-1}A$, then it follows from Proposition 3 that the convex hull of the orbit of x_* under A is an (n-2)-dimensional affine space that we will name V_{x_*} . Furthermore, the orbit Ax_* forms a lattice in the space V_{x_*} .

We let $g^{-1}\mathcal{A}(\infty)$ be the visual boundary of $g^{-1}\mathcal{A}$ in the Tits boundary of X. Recall that the Tits boundary of X is isomorphic to the spherical building for $SL_n(\mathbb{Q}((t^{-1})))$. The definition of visual boundary used above is the standard definition from CAT(0) geometry.

The visual boundary of V_{x_*} is clearly an equatorial sphere in $g^{-1}\mathcal{A}(\infty)$. Precisely, we let P^- be the transpose of P. Then P and P^- are opposite vertices in $g^{-1}\mathcal{A}(\infty)$. It follows that there is a unique sphere in $g^{-1}\mathcal{A}(\infty)$ that is realized by all points equidistant to P and P^- . We call this sphere S_{P,P^-} .

Lemma 7. The visual boundary of V_{x_*} equals S_{P,P^-} .

Proof. Since $g \in P \cap P^-$, it suffices to prove that gV_{x_*} is the sphere in the boundary of \mathcal{A} that is determined by the vertices P and P^- .

Note that gV_{x_*} is a finite Hausdorff distance from any orbit of a point in \mathcal{A} under the action of the diagonal subgroup of L. The result follows by observing that the inverse transpose map on $SL_n(\mathbb{Q}((t^{-1})))$ stabilizes diagonal matrices while interchanging P and P^- .

We let $R_1, R_2, \ldots, R_{n-1}$ be the standard root subgroups of $R_u(P)$. Recall that associated to each R_i there is a closed geodesic hemisphere $H_i \subseteq \mathcal{A}(\infty)$ such that any nontrivial element of R_i fixes H_i pointwise and translates any point in the open hemisphere $\mathcal{A}(\infty) - H_i$ outside of $\mathcal{A}(\infty)$. Note that ∂H_i is a codimension 1 geodesic sphere in $\mathcal{A}(\infty)$. We let $M \subseteq g^{-1}\mathcal{A}(\infty)$ be the union of chambers in $g^{-1}\mathcal{A}(\infty)$ that contain the vertex *P*. There is also an equivalent geometric description of *M*:

Lemma 8. The union of chambers $M \subseteq g^{-1}\mathcal{A}(\infty)$ can be realized as an (n-2)-simplex. Furthermore,

$$M = \bigcap_{i=1}^{n-1} g^{-1} H_i$$

and, when M is realized as a single simplex, each of the n-1 faces of M is contained in a unique equatorial sphere $g^{-1}\partial H_i = \partial g^{-1}H_i$.

Proof. Let $M' \subseteq \mathcal{A}(\infty)$ be the union of chambers in $\mathcal{A}(\infty)$ containing the vertex P. Since $M = g^{-1}M'$, it suffices to prove that M' is an (n-2)-simplex with $M' = \bigcap_{i=1}^{n-1} H_i$ and with each face of M' contained in a unique ∂H_i .

For any nonempty, proper subset $I \subseteq \{1, 2, ..., n\}$, we let V_I be the |I|-dimensional vector subspace of $\mathbb{Q}((t^{-1}))^n$ spanned by the coordinates given by I, and we let P_I be the stabilizer of V_I in $SL_n(\mathbb{Q}((t^{-1})))$. For example, $P = P_{\{1,2,...,n-1\}}$.

Recall that the vertices of $\mathcal{A}(\infty)$ are given by the parabolic groups P_I , that edges connect P_I and $P_{I'}$ exactly when $I \subseteq I'$ or $I' \subseteq I$, and that the remaining simplicial description of $\mathcal{A}(\infty)$ is given by the condition that $\mathcal{A}(\infty)$ is a flag complex.

We let \mathcal{V} be the set of vertices in $\mathcal{A}(\infty)$ of the form P_J where $\emptyset \neq J \subseteq \{1, 2, \ldots, n-1\}$. Note that M' is exactly the set of vertices \mathcal{V} together with the simplices described by the incidence relations inherited from $\mathcal{A}(\infty)$. Thus, M' is easily seen to be isomorphic to a barycentric subdivision of an abstract (n-2)-simplex. Indeed, if $\overline{M'}$ is the abstract simplex on vertices $P_{\{1\}}, P_{\{2\}}, \ldots, P_{\{n-1\}}$, then a simplex of dimension k in $\overline{M'}$ corresponds to a unique $P_J \in \mathcal{V}$ with |J| = k + 1. So we have that M' can be topologically realized as an (n-2)-simplex.

Let F_i be a face of the simplex $\overline{M'}$. Then there is some $1 \le i \le n-1$ such that the set of vertices of F_i is exactly $\{P_{\{1\}}, P_{\{2\}}, \ldots, P_{\{n-1\}}\} - P_{\{i\}}$.

Note that $R_i V_I = V_I$ exactly when $n \in I$ implies $i \in I$. It follows that R_i fixes M' pointwise, and thus $M' \subseteq H_i$ for all $1 \le i \le n-1$. Furthermore, if $P_I \in H_i$ for all $1 \le i \le n-1$, then $R_i P_I = P_I$ for all i so that $n \in I$ implies $i \in I$ for all $1 \le i \le n-1$. As I must be a proper subset of $\{1, 2, ..., n\}$, we have $P_I \in \mathcal{V}$, so that $M' = \bigcap_{i=1}^{n-1} H_i$.

All that remains to be verified for this lemma is that $F_i \subseteq \partial H_i$. For this fact, recall that F_i is comprised of (n-3)-simplices in $\mathcal{A}(\infty)$ whose vertices are given by P_J where $J \subseteq \{1, 2, ..., n-1\} - \{i\}$. Hence, if $\sigma \subseteq \mathcal{A}(\infty)$ is an (n-3)simplex of $\mathcal{A}(\infty)$ with $\sigma \subseteq F_i$, then σ is a face of exactly 2 chambers in $\mathcal{A}(\infty)$: \mathfrak{C}_P and $\mathfrak{C}_{P_{J'}}$ where \mathfrak{C}_P contains P and thus $\mathfrak{C}_P \subseteq M'$, and $\mathfrak{C}_{P_{J'}}$ contains $P_{J'}$ where $J' = \{1, 2, ..., n\} - \{i\}$ and thus $\mathfrak{C}_{P_{J'}} \not\subseteq M'$. Furthermore, $\sigma = \mathfrak{C}_P \cap \mathfrak{C}_{P_{J'}}$.

Since $R_i V_{J'} \neq V_{J'}$, it follows that $\mathfrak{C}_{P_{J'}}$ is not fixed by R_i . Since \mathfrak{C}_{P_J} is fixed by R_i we have that $\sigma = \mathfrak{C}_P \cap \mathfrak{C}_{P_{J'}} \subseteq \partial H_i$. Therefore, $F_i \subseteq \partial H_i$.

For any vertex $y \in X$, we let $C_y \subseteq X$ be the union of sectors based at y and limiting to a chamber in M. Thus, C_y is a cone. Note also that because any chamber in $g^{-1}\mathcal{A}(\infty)$ has diameter less than $\pi/2$, it follows that $M \cap S_{P,P^-} = \emptyset$. Therefore, if we choose $x_*, y \in g^{-1}\mathcal{A}$ such that x_* is closer to P than y, then $C_y \subseteq g^{-1}\mathcal{A}$ and $V_{x_*} \cap C_y$ is a simplex of dimension n-2.

We will set on a fixed choice of y before x_* , and we will choose y to satisfy the below

Lemma 9. There is some $y \in g^{-1}A$ such that the $\mathbb{Q}[[t^{-1}]]$ -points of $R_u(P)$ fix C_y pointwise.

Proof. Let x_0 be the point in X stabilized by $SL_n(\mathbb{Q}[[t^{-1}]])$. Recall that $R_u(P)M = M$ so that the $\mathbb{Q}[[t^{-1}]]$ -points of $R_u(P)$ fix C_{x_0} pointwise.

Because $M \subseteq g^{-1}\mathcal{A}(\infty)$, there is a $y \in C_{x_0} \cap g^{-1}\mathcal{A}$. Any such y satisfies the lemma.

Choose *e* such that with $x_* = e$ as above and with *y* as in Lemma 9, there exists a fundamental domain D_e for the action of *A* on V_e that is contained in C_y . The choice of *e* can be made by travelling arbitrarily far from *y* along a geodesic ray in $g^{-1}A$ that limits to *P*.

By the choice of D_e we have that

 $AD_e = V_e$

and that the $\mathbb{Q}([[t^{-1}]])$ -points of $R_u(P)$ fix D_e .

4.2. The filtration. We let

$$X_0 = \mathrm{SL}_n(\mathbb{Z}[t]) D_e$$

and for any $i \in \mathbb{N}$ we choose an $SL_n(\mathbb{Z}[t])$ -invariant and cocompact space $X_i \subseteq X$ somewhat arbitrarily to satisfy the inclusions

$$X_0 \subseteq X_1 \subseteq X_2 \subseteq \cdots \subseteq \bigcup_{i=1}^{\infty} X_i = X.$$

In our present context, Brown's criterion takes on the following form [Br1].

Brown's Filtration Criterion. By Lemma 2, the group $SL_n(\mathbb{Z}[t])$ is not of type FP_{n-1} if for any $i \in \mathbb{N}$, there exists some class in the homology group $\widetilde{H}_{n-2}(X_0, \mathbb{Z})$ which is nonzero in $\widetilde{H}_{n-2}(X_i, \mathbb{Z})$.

4.3. Translation to *P* moves away from filtration sets. The following is essentially Mahler's compactness criterion.

Lemma 10. Given any $i \in \mathbb{N}$, there is some $k \in \mathbb{N}$ such that $b^k e \notin X_i$.

Proof. The lemma follows from showing that the sequence

$$\{\mathrm{SL}_n(\mathbb{Z}[t])b^k e\}_k \subseteq \mathrm{SL}_n(\mathbb{Z}[t]) \setminus X$$

is unbounded.

Since stabilizers of points in X are bounded subgroups of $SL_n(\mathbb{Q}((t^{-1})))$, the claim above follows from showing that the sequence

$$\{\mathrm{SL}_n(\mathbb{Z}[t])b^k\}_k \subseteq \mathrm{SL}_n(\mathbb{Z}[t]) \setminus \mathrm{SL}_n(\mathbb{Q}((t^{-1})))$$

is unbounded.

But bounded sets in $SL_n(\mathbb{Z}[t]) \setminus SL_n(\mathbb{Q}((t^{-1})))$ do not contain sequences of elements $\{SL_n(\mathbb{Z}[t])g_\ell\}_\ell$ such that $1 \in \overline{g_\ell}^{-1}(SL_n(\mathbb{Z}[t]) - \{1\})g_\ell$. And clearly b^k 's contract some root groups to 1. Thus none of the sequences above is bounded. \Box

4.4. Applying Brown's criterion. As is described by Brown's criterion, we will prove Theorem 1 by fixing X_i and finding an (n-2)-cycle in X_0 that is nontrivial in the homology of X_i .

Recall that we denote the standard root subgroups of $R_u(P)$ by R_1, \ldots, R_{n-1} . Each group $g^{-1}R_jg$ determines a family of parallel walls in $g^{-1}A$. By Lemma 8, each face of the cone C_{γ} is contained in a wall of one of these families.

Choose $r_j \in g^{-1}R_jg$ for all j such that $b^k e$ is contained in the wall determined by r_j where k is determined by i as in Lemma 10. In particular, $r_j b^k e = b^k e$.

The intersection of the fixed point sets in $g^{-1}A$ of the elements r_1, \ldots, r_{n-1} determine a cone that we name Z. Note that Z is contained in – and is a finite Hausdorff distance from – the cone C_y .

Let $Z^- \subseteq g^{-1}A$ be the closure of the set of points in $g^{-1}A$ that are fixed by none of the r_j . The set Z^- is a cone based at $b^k e$, containing y, and asymptotically containing the vertex P^- .

As the walls of Z^- are parallel to those of Z – and hence of C_y , we have that $Z^- \cap V_e$ is an (n-2)-dimensional simplex. We will name this simplex σ .

The component of $Z^- - V_e$ that contains $b^k e$ is an (n-1)-simplex that has σ as a face. Call this (n-1) simplex Y.

For any $\ell \in \mathbb{N}$, there are exactly 2^{n-1} possible subsets of the set $\{r_1^{\ell}, \ldots, r_{n-1}^{\ell}\}$. For each such subset S_{ℓ} , we let

$$Y_{S_{\ell}} = \Big(\prod_{g \in S_{\ell}} g\Big)Y$$

and

$$\sigma_{S_\ell} = \Big(\prod_{g \in S_\ell} g\Big)\sigma.$$

Notice that the product of group elements in the equations above are well-defined regardless of the order of the multiplication since $R_u(P)$ is abelian. In the degenerate cases, $\prod_{g \in \emptyset} g = 1$, so $Y_{\emptyset} = Y$ and $\sigma_{\emptyset} = \sigma$.

For any $\ell \in \mathbb{N}$, we let $Y_{\ell} = \bigcup_{S_{\ell}} Y_{S_{\ell}}$. Because the wall in $g^{-1}\mathcal{A}$ determined by r_j^{ℓ} is the same as the wall determined by r_j , the space Y_{ℓ} is a closed ball containing $b^k e$ whose boundary sphere is $\bigcup_{S_{\ell}} \sigma_{S_{\ell}}$. Indeed the simplicial decomposition of Y_{ℓ} described above is isomorphic to the simplicial decomposition of the unit ball in \mathbb{R}^{n-1} that is given by the n-1 hyperplanes defined by setting a coordinate equal to 0.

Let $\omega_{\ell} = \bigcup_{S_{\ell}} \sigma_{S_{\ell}}$. Thus $\omega_{\ell} = \partial Y_{\ell}$. Furthermore, the building X is (n-1)-dimensional and contractible, so any (n-1)-chain with boundary equal to ω_{ℓ} must contain Y_{ℓ} and thus $b^k e$. That is for all $\ell \in \mathbb{N}$

$$[\omega_{\ell}] \neq 0 \in \tilde{H}_{n-2}(X - b^k e, \mathbb{Z})$$

If we can show that $\omega_{\ell} \subseteq X_0$ for some choice of ℓ , then we will have proved our main theorem by application of Brown's criterion since we would have

$$[\omega_{\ell}] \neq 0 \in \tilde{H}_{n-2}(X_i, \mathbb{Z})$$

by Lemma 10.

Lemma 11. There exists some $\ell \in \mathbb{N}$ such that $\omega_{\ell} \subseteq X_0$.

Proof. For any $u \in R_u(P)$ there is a decomposition u = u'u'' where the entries of $u' \in R_u(P)$ are contained in $\mathbb{Q}[t]$ and the entries of $u'' \in R_u(P)$ are contained in $\mathbb{Q}[[t^{-1}]]$.

For any $a \in A$ and $u \in R_u(P)$ there is a power $\ell(a, u) \in \mathbb{N}$ such that

$$(a^{-1}u^{\ell(a,u)}a)' = ((a^{-1}ua)')^{\ell(a,u)} \in \mathrm{SL}_n(\mathbb{Z}[t]).$$

(For the above equality recall that $A \leq L$ normalizes $R_u(P)$ and the group operation on $R_u(P)$ is vector addition.)

There are only finitely many $a \in A$ such that $a D_e \cap \sigma \neq \emptyset$ (or equivalently, such that $a D_e \cap Z^- \neq \emptyset$). Call this finite set $\mathcal{D} \subseteq A$.

At this point we fix

$$\ell = \prod_{a \in \mathcal{D}} \prod_{i=1}^{n-1} \ell(a, r_i).$$

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Thus,

$$\left[a^{-1}\left(\prod_{g\in S_{\ell}}g\right)a\right]'\in \mathrm{SL}_n(\mathbb{Z}[t])$$

for any $a \in \mathcal{D}$ and any $S_{\ell} \subseteq \{r_i^{\ell}\}_{i=1}^{n-1}$. Because $\omega_{\ell} = \bigcup_{S_{\ell}} \sigma_{S_{\ell}}$ and $\sigma_{S_{\ell}} = (\prod_{g \in S_{\ell}} g)\sigma = (\prod_{g \in S_{\ell}} g)(AD_e \cap Z^-)$, we can finish our proof of this lemma by showing

$$\Big(\prod_{g\in S_\ell}g\Big)aD_e\subseteq X_0$$

for each $a \in \mathcal{D} \subseteq A \leq \mathrm{SL}_n(\mathbb{Z}[t])$ and each $S_\ell \subseteq \{r_i^\ell\}_{i=1}^{n-1}$. For this, recall that the $\mathbb{Q}[[t^{-1}]]$ -points of $R_u(P)$ fix D_e and thus

$$\left(\prod_{g \in S_{\ell}} g\right) a D_{e} = a[a^{-1} \left(\prod_{g \in S_{\ell}} g\right) a] D_{e}$$
$$= a[a^{-1} \left(\prod_{g \in S_{\ell}} g\right) a]'[a^{-1} \left(\prod_{g \in S_{\ell}} g\right) a]'' D_{e}$$
$$= a[a^{-1} \left(\prod_{g \in S_{\ell}} g\right) a]' D_{e}$$
$$\subseteq SL_{n}(\mathbb{Z}[t]) D_{e}$$
$$= X_{0}$$

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