# §4. Superpositions of continuons functions

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the same time, from the inequalities mentioned above it follows that an increase in k leads to an insignificant improvement in the accuracy of the approximation. Hence, in a certain sense, a more economical approximation of functions is by means of expressions of the given form with k = 1, that is, by fractions of the form

$$\frac{\sum_{i=0}^{p} a_i f_i(x)}{\sum_{j=0}^{p} b_j g_j(x)}$$

The same inequalities with k = 1 show that there are no methods of approximating functions by fractions of the given form essentially better than the standard methods of approximating functions by algebraic (or trigonometric) polynomials.

## § 4. Superpositions of continuous functions

Kolmogorov's theorem on the possibility of representing continuous functions of n variables as superpositions of continuous functions of three variables was highly unexpected (see [7]).

In this paper Kolmogorov proves that on the *n*-dimensional cube  $\mathscr{I}^n$  we can construct continuous functions  $\varphi_i(x)$  (i = 1, 2, ..., n+1) such that any continuous function f(x), defined on the cube  $\mathscr{I}^n$ , can be represented in the form

$$f(x) = \sum_{i=1}^{n+1} f_i(d_i(x)),$$

where  $d_i(x)$  is a continuous mapping of  $\mathscr{I}^n$  onto the one-dimensional tree<sup>1</sup>) D if the components of the level sets of the functions  $\varphi_i(x)$ , and  $f_i(d_i)$ is a continuous function on the tree  $D_i$ . Since the trees  $\{D_i\}$  can be embedded homeomorphically in the plane (see [30]), the functions  $\{f_i(d_i(x))\}$ can be thought of as superpositions

$$\{f_i(u_i(x_1, x_2, ..., x_n), v_i(x_1, x_2, ..., x_n))\}$$

<sup>&</sup>lt;sup>1</sup>) Kronrod [29] has shown that the components of all possible level sets of any continuous function defined on  $\mathscr{I}^n$  in a certain natural topology, form a tree, that is, a one-dimensional locally connected continuum, not containing homeomorphic images of circles. Kronrod calls this the "one-dimensional tree of the function".

where  $\{f_i(u_i, v_i)\}$  are continuous functions of two variables, and  $\{u_i(x)\}$ and  $\{v_i(x)\}$  are fixed continuous functions of *n* variables. Kolmogorov derived from this the result that for  $n \ge 4$  any continuous function of *n* variables can be represented by the following superposition of continuous functions of not more than n - 1 variables:

$$\sum_{i=1}^{n} f_i \left( u_i \left( x_1, x_2, \dots, x_{n-1} \right), v_i \left( x_1, x_2, \dots, x_{n-1} \right), x_n \right).$$

Arnol'd [8], [22] showed that, firstly, in Kolmogorov's construction [7] we can manage with functions {  $\varphi_i(x)$  } whose one-dimensional trees {  $D_i$  } have index at each branch point equal to 3, and, secondly, for any compact set F of functions defined on such a tree D, the given tree can be so placed in three-dimensional u, v, w-space that any continuous function f(d)=  $f(u, v, w) \in F$  can be represented as the sum of functions of the coordinates,  $f(u, v, w) = \varphi(u) + \psi(v) + \kappa(w)$ . Hence it follows that any continuous function f(x, y, z) of three variables can be represented as a superposition of the form  $f(x, y, z) = \sum_{i=1}^{9} f_i(\varphi_i(x, y), z)$ , where all the functions are continuous, and the functions {  $\varphi_i(x, y)$  } can be regarded as fixed, when f(x, y, z) is taken from a compact set. Thus, Arnol'd had the last word in refuting Hilbert's conjecture. At the same time Kolmogorov [9] obtained, in a certain sense, the definitive result in this direction.

Each continuous function of n variables, given on the unit cube in n-dimensional space, is representable as a superposition of the form

$$f(x_1, x_2, ..., x_n) = \sum_{q=1}^{2n+1} g_q \left( \sum_{p=1}^n \varphi_{p,q} \left( x_p \right) \right) , \qquad (I)$$

where all the functions are continuous, and moreover the functions  $\{\varphi_{p,q}(x_p)\}$  are standard and monotonic.

In particular, each continuous function of two variables is representable in the form

$$f(x, y) = \sum_{i=1}^{5} f_i(a_i(x) + \beta_i(y)).$$
(II)

Kolmogorov's theorem can be supplemented by the following result of Bari, which was obtained in connection with problems of Fourier series: any continuous function of one variable f(t) can be represented in the form  $f(t) = f_1(\varphi_1(t)) + f_2(\varphi_2(t)) + f_3(\varphi_3(t))$ , where all the functions  $\{f_i\}$  and  $\{\varphi_i\}$  are absolutely continuous [32].

From the theorems of Kolmogorov and Bari it follows that each continuous function of n variables can be represented as a superposition of absolutely continuous monotonic functions of one variable and the operation of addition.

A detailed account of Kolmogorov's theorem is to be found in the surveys [9], [33]-[36]. The proof presented by Kahane is of special interest [36]. He does not attempt to construct the functions {  $\varphi_{p,q}$  } (as the proof of Kolmogorov does) but instead he shows by means of Baire's theorem, that most selections of increasing functions {  $\varphi_{pq}$  } will do. This approach also lead to other interesting results.

Fridman [37] showed that the inner functions  $\{\varphi_{pq}\}$  can be chosen from the class Lip 1. Kahane noticed that this follows directly from Kolmogorov's theorem. For any finite collection of continuous and monotone functions  $\{f_k(x)\}$  on the segment [0, 1] there exists a homeomorphism  $x = \varphi(s)$  of the segment [0, 1] onto itself such that the functions  $\{g_k(s)\}$  $= f_k(\varphi(s))\}$  belong to the class Lip 1. The homeomorphism is taken as

$$s = \varphi^{-1}(x) = \varepsilon \left( x + \sum_{k} |f_{k}(x) - f_{k}(0)| \right).$$

The constant  $\varepsilon$  is chosen to satisfy the condition  $\varphi^{-1}(1) = 1$ . By means of such homeomorphisms all inner functions in Kolmogorov's formula can be turned into functions satisfying the condition Lip 1.

There are some other improvements of Kolmogorov's theorem: Doss [38], Bassalygo [39], Lorentz [34], Sprecher [40] (see chapter 3, § 1). There are also many results concerning special types of superpositions (see [21], [33], [41]-[44]).

### § 5. Linear superpositions

We return again to superpositions of smooth functions.

One of the most interesting current problems on the subject of superpositions is the following: does there exist an analytic function of two variables that cannot be represented as a finite superposition of continuously differentiable (smooth) functions of one variable and the operation of addition?

Linear superpositions arise as a result of the following argument. Suppose that a function of two variables f(x, y) is an *s*-fold superposition of certain smooth functions of one variable  $\{f_i(t)\}$  and the operation of addition. We vary this superposition, that is, we consider a superposition